Multi-Threading in C++
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In C++ it is allowed to run multiple threads simultaneously that use the same memory.

- Multiple threads may *read* from the same memory location
- All other accesses (i.e. read-write, write-read, write-write) are called *conflicts*
- Conflicting operations are only allowed when threads are *synchronized*
- This can be done with *mutexes* or *atomic operations*
- Unsynchronized accesses (also called *data races*), deadlocks, and other potential issues when using threads are undefined behavior!

All conflicting operations must be synchronized in some way!
Threads Library (1)

The header `<thread>` defines the class `std::thread`

- Using this class is the best way to use threads platform-independently
- May require additional compiler flags depending on the actual underlying implementation
- Use CMake to determine these flags in a platform-independent way
- For gcc and clang on Linux this will usually be `-pthread`

```cpp
cmake_minimum_required(VERSION 3.21)
project(sample)

find_package(Threads REQUIRED)
add_executable(sample main.cpp)
target_link_libraries(sample PUBLIC Threads::Threads)
```
Threads Library (2)

The constructor of `std::thread` can be used to start a new thread

- Syntax: `thread(Function&& f, Args&&... args)`
- The function `f` will be invoked in a new thread with the arguments `args`
- The thread will terminate once `f` returns
- The default constructor can be used to create an empty thread object

The member function `join()` must be used to wait for a thread to finish

- `join()` must be called exactly once for each thread
- `join()` must be called *before* an `std::thread` object is destroyed
- When the destructor of an `std::thread` is called, the program is terminated if the associated thread was not joined
Example

```cpp
#include <thread>

void foo(int a, int b);

int main() {
    // Pass a function and args
    std::thread t1(foo, 1, 2);
    // Pass a lambda
    std::thread t2([]() {
        foo(3, 4);
    });

    foo(5, 6);

    t2.join();
    t1.join();
}
```
Example

```cpp
#include <iostream>
#include <string_view>
#include <thread>

void safe_print(std::string_view s);

int main() {
    {
        std::thread t1([]() { safe_print("Hi\n"); });
        t1.join();
    }
    // Everything is fine, we called t1.join()
    {
        std::thread t2([]() {});
    }
    // Program terminated because t2.join() was not called
}
```
Threads Library (5)

std::thread is movable but not copyable

- Moving transfers all resources associated with the running thread
- Only the moved-to thread can be joined
- The moved-from thread object is empty (not associated with any thread)

Example

```cpp
#include <iostream>
#include <string_view>
#include <thread>

void safe_print(std::string_view s);

int main() {
    std::thread t1([]() { safe_print("Hi\n"); });
    std::thread t2 = std::move(t1); // t1 is now empty
    t2.join(); // OK, thread originally started in t1 is joined
}
```
std::thread can be used in standard library containers

```cpp
#include <thread>
#include <vector>

void safe_print(int i);

int main() {
    std::vector<std::thread> threadPool;
    for (int i = 1; i <= 9; ++i) {
        threadPool.emplace_back([i]() { safe_print(i); });
    }
    // Digits 1 to 9 are printed (unordered)
    for (auto& t : threadPool) {
        t.join();
    }
}
```
The thread library also contains other useful functions that are closely related to starting and stopping threads:

- `std::this_thread::sleep_for()`: Stop the current thread for a given amount of time
- `std::this_thread::sleep_until()`: Stop the current thread until a given point in time
- `std::this_thread::yield()`: Let the operating system schedule another thread
- `std::this_thread::get_id()`: Get the (operating-system-specific) id of the current thread
Mutual Exclusion (1)

*Mutual exclusion* is a straightforward way to synchronize multiple threads

- Threads acquire a lock on a mutex object before entering a critical section
- Threads release their lock on the mutex when leaving a critical section

**High-level programming model**

- The resource (usually a class) that requires protection from data races owns a mutex object of the appropriate type
- Threads that intend to access the resource acquire a suitable lock on the mutex *before* performing the actual access
- Threads release their lock on the mutex *after* completing the access
- Usually locks are simply acquired and released in the member functions of the class
Mutual Exclusion (2)

The standard library defines several useful classes that implement mutexes in the `<mutex>` and `<shared_mutex>` headers

- `std::mutex` – regular mutual exclusion
- `std::recursive_mutex` – recursive mutual exclusion
- `std::shared_mutex` – mutual exclusion with shared locks

The standard library provides RAII wrappers for locking and unlocking mutexes

- `std::unique_lock` – RAII wrapper for exclusive locking
- `std::shared_lock` – RAII wrapper for shared locking

The RAII wrappers should *always* be preferred for locking and unlocking mutexes

- Makes bugs due to inconsistent locking/unlocking much more unlikely
- Manual locking and unlocking may be required in some rare cases
- Should still be performed through the corresponding functions of the RAII wrappers
std::unique_lock (1)

std::unique_lock can be used to lock a mutex in exclusive mode

- The constructor acquires an exclusive lock on the mutex
- Constructor syntax: `unique_lock(mutex_type& m)`
- Blocks the calling thread until the mutex becomes available
- The destructor releases the lock automatically
- Can be used with any mutex type from the standard library

```cpp
#include <mutex>
#include <iostream>

std::mutex printMutex;
void safe_print(int i) {
    std::unique_lock lock(printMutex); // lock is acquired
    std::cout << i;
} // lock is released
```
std::unique_lock(2)

std::unique_lock provides additional constructors
- `unique_lock(mutex_type& m, std::defer_lock_t t)` – Do not immediately lock the mutex
- `unique_lock(mutex_type& m, std::try_to_lock_t t)` – Do not block when the mutex cannot be locked

std::unique_lock provides additional member functions
- `lock()` – Manually lock the mutex
- `try_lock()` – Try to lock the mutex, return `true` if successful
- `operator bool()` – Check if the `std::unique_lock` holds a lock on the mutex
std::unique_lock (3)

Example

```cpp
#include <mutex>

std::mutex mutex;

void foo() {
    std::unique_lock lock(mutex, std::try_to_lock);
    if (!lock) {
        doUnsynchronizedWork();

        // block until we can get the lock
        lock.lock();
    }

doSynchronizedWork();

    // release the lock early
    lock.unlock();

    doUnsynchronizedWork();
}
```
std::unique_lock (4)

std::unique_lock is movable to transfer ownership of a lock on a mutex

```cpp
#include <mutex>

class MyContainer {
    private:
        std::mutex mutex;

    public:
        class iterator { /* ... */ };  

        iterator begin() {
            std::unique_lock lock(mutex);

            // compute the begin iterator constructor args
            // keep the lock for iteration
            return iterator(std::move(lock), ...);
        }
};
```
Recursive Mutexes (1)

The following code will deadlock since `std::mutex` can be locked at most once.

```cpp
#include <mutex>

std::mutex mutex;

void bar() {
    std::unique_lock lock(mutex);

    // do some work...
}

void foo() {
    std::unique_lock lock(mutex);

    // do some work...

    bar(); // INTENTIONALLY BUGGY, will deadlock
}
```
Recursive Mutexes (2)

`std::recursive_mutex` implements recursive ownership semantics
- The same thread can lock an `std::recursive_mutex` multiple times without blocking
- Other threads will still block if an `std::recursive_mutex` is currently locked
- Can be used with `std::unique_lock` just like a regular `std::mutex`
- Useful for functions that call each other and use the same mutex

```cpp
#include <mutex>

std::recursive_mutex mutex;
void bar() {
    std::unique_lock lock(mutex);
}
void foo() {
    std::unique_lock lock(mutex);
    bar(); // OK, will not deadlock
}
```
std::shared_lock (1)

std::shared_lock can be used to lock a mutex in shared mode
- Constructors and member functions analogous to std::unique_lock
- Multiple threads can acquire a shared lock on the same mutex
- Shared locking attempts block if the mutex is locked in exclusive mode
- Only usable in conjunction with std::shared_mutex

We have to adhere to some contract to write well-behaved programs
- Shared mutexes are mostly used to implement read/write-locks
- Only read accesses are allowed when holding a shared lock
- Write accesses are only allowed when holding an exclusive lock
std::shared_lock (2)

Example

```cpp
#include <shared_mutex>

class SafeCounter {
    private:
        mutable std::shared_mutex mutex;
        size_t value = 0;

    public:
        size_t getValue() const {
            std::shared_lock lock(mutex);
            return value; // read access
        }

        void incrementValue() {
            std::unique_lock lock(mutex);
            ++value; // write access
        }
};
```
We usually have to make mutexes `mutable` within our data structures

- The RAII wrappers require mutable references to the mutex
- `const` member functions of our data structure usually also need to use the mutex

Using mutexes without care can easily lead to deadlocks within the system

- Usually occurs when a thread tries to lock another mutex when it already holds a lock on some mutex
- Can in some cases be avoided by using `std::recursive_mutex` (if we are locking the same mutex multiple times)
- Requires dedicated programming techniques when multiple mutexes are involved
Avoiding Deadlocks (1)

The following example will lead to deadlocks

```cpp
std::mutex m1, m2, m3;
void threadA() {
    // INTENTIONALLY BUGGY
    std::unique_lock l1{m1}, l2{m2}, l3{m3};
}
void threadB() {
    // INTENTIONALLY BUGGY
    std::unique_lock l3{m3}, l2{m2}, l1{m1};
}
```

Possible deadlock scenario

- `threadA()` acquires locks on `m1` and `m2`
- `threadB()` acquires lock on `m3`
- `threadA()` waits for `threadB()` to release `m3`
- `threadB()` waits for `threadA()` to release `m2`
Avoiding Deadlocks (2)

Deadlocks can be avoided by always locking mutexes in a *globally* consistent order

- Ensures that one thread always “wins”
- Maintaining a globally consistent locking order requires considerable developer discipline
- Maintaining a globally consistent locking order may not be possible at all

```cpp
std::mutex m1, m2, m3;
void threadA() {
    // OK, will not deadlock
    std::unique_lock l1{m1}, l2{m2}, l3{m3};
}
void threadB() {
    // OK, will not deadlock
    std::unique_lock l1{m1}, l2{m2}, l3{m3};
}
```
Avoiding Deadlocks (3)

Sometimes it is not possible to guarantee a globally consistent order

- The std::scoped_lock RAII wrapper can be used to safely lock any number of mutexes
- Employs a deadlock-avoidance algorithm if required
- Generally quite inefficient in comparison to std::unique_lock
- Should only be used as a last resort!

```cpp
std::mutex m1, m2, m3;
void threadA() {
    // OK, will not deadlock
    std::scoped_lock l{m1, m2, m3};
}
void threadB() {
    // OK, will not deadlock
    std::scoped_lock l{m3, m2, m1};
}
```
Condition Variables (1)

A condition variable is a synchronization primitive that allows multiple threads to wait until an (arbitrary) condition becomes true.

- A condition variable uses a mutex to synchronize threads
- Threads can wait on or notify the condition variable
- When a thread waits on the condition variable, it blocks until another thread notifies it
- If a thread waited on the condition variable and is notified, it holds the mutex
- A notified thread must check the condition explicitly because spurious wake-ups can occur
The standard library defines the class `std::condition_variable` in the header `<condition_variable>` which has the following member functions:

- **wait()**: Takes a reference to a `std::unique_lock` that must be locked by the caller as an argument, unlocks the mutex and waits for the condition variable.
- **notify_one()**: Notify a single waiting thread, mutex does not need to be held by the caller.
- **notify_all()**: Notify all waiting threads, mutex does not need to be held by the caller.
Condition Variables Example

One use case for condition variables are worker queues: Tasks are inserted into a queue and then worker threads are notified to do the task.

```cpp
std::mutex m;
std::condition_variable cv;
std::vector<int> taskQueue;

void pushWork(int task) {
    {
        std::unique_lock l{m};
        taskQueue.push_back(task);
    }
    cv.notify_one();
}

void workerThread() {
    std::unique_lock l{m};
    while (true) {
        while (!taskQueue.empty()) {
            int task = taskQueue.back();
            taskQueue.pop_back();
            l.unlock();
            // [...] do actual work here
            l.lock();
        }
        cv.wait(l);
    }
}
```
Atomic Operations

Mutual exclusion may be inefficient for synchronization

- Very coarse-grained synchronization
- May require communication with the operating system

Modern hardware also supports *atomic operations* for synchronization.

- The memory order of a CPU determines how *non-atomic* memory operations are allowed to be reordered
- In C++ all non-atomic conflicting operations have undefined behavior even if the memory order of the CPU would allow it!
- There is one exception: Special atomic functions are allowed to have conflicts
- The compiler usually knows your CPU and generates “real” atomic instructions only if necessary
C++ provides atomic operations in the atomic operations library

- Implemented in the `<atomic>` header
- `std::atomic<T>` is a class that represents an atomic version of the type T
- Can be used (almost) interchangeably with the original type T
- Has the same size and alignment as the original type T
- Conflicting operations are only allowed on `std::atomic<T>` objects

`std::atomic` on its own does not provide any synchronization at all

- Simply makes conflicting operations possible and defined behavior
- Exposes the guarantees of specific memory models to the programmer
- Suitable programming models must be used to achieve proper synchronization
std::atomic has several member functions that implement atomic operations

- `T load()`: Loads the value
- `void store(T desired)`: Stores desired in the object
- `T exchange(T desired)`: Stores desired in the object and returns the old value

If `T` is a integral type, the following operations also exist:

- `T fetch_add(T arg)`: Adds `arg` to the value and returns the old value
- `T fetch_sub(T arg)`: Same for subtraction
- `T fetch_and(T arg)`: Same for bitwise and
- `T fetch_or(T arg)`: Same for bitwise or
- `T fetch_xor(T arg)`: Same for bitwise xor
Example (without atomics)

```c
#include <thread>

int main() {
    unsigned value = 0;
    thread t([]() {
        for (size_t i = 0; i < 10; ++i)
            ++value; // UNDEFINED BEHAVIOR, data race
    });

    for (size_t i = 0; i < 10; ++i)
        ++value; // UNDEFINED BEHAVIOR, data race

    t.join();

    // value will contain garbage
}
```
## Atomic Operations Library (4)

### Example (with atomics)

```cpp
#include <atomic>
#include <thread>

int main() {
    std::atomic<unsigned> value = 0;
    thread t([]() {
        for (size_t i = 0; i < 10; ++i)
            value.fetch_add(1); // OK, atomic increment
    });

    for (size_t i = 0; i < 10; ++i)
        value.fetch_add(1); // OK, atomic increment

    t.join();

    // value will contain 20
}
```
Semantics of Atomic Operations

C++ may support atomic operations that are not supported by the CPU

- `std::atomic<T>` can be used with any trivially copyable type
- In particular also for types that are much larger than one cache line
- To guarantee atomicity, compilers are allowed to fall back to mutexes

The C++ standard defines precise semantics for atomic operations

- Every atomic object has a totally ordered *modification order*
- There are several *memory orders* that define how operations on different atomic objects may be reordered
- The C++ memory orders do not necessarily map precisely to memory orders defined by a CPU
Modification Order (1)

All modifications of a *single* atomic object are totally ordered

- This is called the *modification order* of the object
- All threads are guaranteed to observe modifications of the object in this order

Modifications of *different* atomic objects may be unordered

- Different threads may observe modifications of multiple atomic objects in a different order
- The details depend on the *memory order* that is used for the atomic operations
Modification Order (2)

Example

```cpp
std::atomic<int> i = 0, j = 0;
void workerThread() {
    i.fetch_add(1); // (A)
    i.fetch_sub(1); // (B)
    j.fetch_add(1); // (C)
}
void readerThread() {
    int iLocal = i.load(), jLocal = j.load();
    assert(iLocal != -1); // always true
}
```

Observations

- Reader threads will never see a modification order with (B) before (A)
- Depending on the memory order, multiple reader threads may see any of (A), (B), (C), or (A), (C), (B), or (C), (A), (B)
Memory Order (1)

The atomics library defines several memory orders:

- All atomic functions take a memory order as their last parameter.
- The two most important memory orders are `std::memory_order_relaxed` and `std::memory_order_seq_cst`.
- `std::memory_order_seq_cst` is used by default if no memory order is explicitly supplied.
- You should stick to this default unless you identified the atomic operation to be a performance bottleneck.

```cpp
std::atomic<int> i = 0;

i.fetch_add(1); // uses std::memory_order_seq_cst
i.fetch_add(1, std::memory_order_seq_cst);
i.fetch_add(1, std::memory_order_relaxed);
```
Memory Order (2)

std::memory_order_relaxed

- Roughly maps to a CPU with weak memory order
- Only consistent modification order is guaranteed
- Atomic operations of different objects may be reordered arbitrarily

```cpp
std::atomic<int> i = 0, j = 0;
void threadA() {
    while (true) {
        i.fetch_add(1, std::memory_order_relaxed); // (A)
        i.fetch_sub(1, std::memory_order_relaxed); // (B)
        j.fetch_add(1, std::memory_order_relaxed); // (C)
    }
}
void threadB() { /* ... */ }
void threadC() { /* ... */ }
```

Observations

- `threadB()` may observe (A), (B), (C)
- `threadC()` may observe (C), (A), (B)
Multi-Threading in C++

Atomic Operations

Memory Order (3)

std::memory_order_seq_cst

- Roughly maps to a CPU with strong memory order
- Guarantees that all threads see all atomic operations in one globally consistent order

```
std::atomic<int> i = 0, j = 0;
void threadA() {
    while (true) {
        i.fetch_add(1, std::memory_order_seq_cst); // (A)
        i.fetch_sub(1, std::memory_order_seq_cst); // (B)
        j.fetch_add(1, std::memory_order_seq_cst); // (C)
    }
}
void threadB() { /* ... */ }
void threadC() { /* ... */ }
```

Observations

- threadB() may observe (C), (A), (B)
- threadC() will then also observe (C), (A), (B)
Compare-And-Swap Operations (1)

Compare-and-swap operations are one of the most useful operations on atomics

- **Signature:** `bool compare_exchange_weak(T& expected, T desired)`
- Compares the current value of the atomic to `expected`
- Replaces the current value by `desired` if the atomic contained the `expected` value and returns `true`
- Updates `expected` to contain the current value of the atomic object and returns `false` otherwise

Often the main building block to synchronize data structures without mutexes

- Allows us to check that no modifications occurred to an atomic over some time period
- Can be used to implement “implicit” mutual exclusion
- Can suffer from subtle problems such as the A-B-A problem
Compare-And-Swap Operations (2)

Example: Insert into a lock-free singly linked list

```cpp
#include <atomic>

class SafeList {
    private:
        struct Entry {
            T value;
            Entry* next;
        }
    
        std::atomic<Entry*> head;

    Entry* allocateEntry(const T& value);

    public:
        void insert(const T& value) {
            auto* entry = allocateEntry(value);
            auto* currentHead = head.load();
            do {
                entry->next = currentHead;
            } while (!head.compare_exchange_weak(currentHead, entry));
        }
};
```
Compare-And-Swap Operations (3)

`std::atomic` actually provides two CAS versions with the same signature:

- `compare_exchange_weak` – weak CAS
- `compare_exchange_strong` – strong CAS

**Semantics**

- The weak version is allowed to return false, even when no other thread modified the value
- This is called “spurious failure”
- The strong version may use a loop internally to avoid this
- General rule: If you use a CAS operation in a loop, always use the weak version
std::atomic can be unwieldy

- std::atomic is neither movable nor copyable
- As a consequence it cannot easily be used in standard library containers

std::atomic_ref allows us to apply atomic operations to non-atomic objects

- The constructor takes a reference to an arbitrary object of type T
- The referenced object is treated as an atomic object during the lifetime of the std::atomic_ref
- std::atomic_ref defines similar member functions to std::atomic

Data races between accesses through std::atomic_ref and non-atomic accesses are still undefined behavior!
std::atomic_ref (2)

Example

```cpp
#include <atomic>
#include <thread>
#include <vector>

int main() {
    std::vector<int> localCounters(4);
    std::vector<std::thread> threads;

    for (size_t i = 0; i < 16; ++i) {
        threads.emplace_back([]() {
            for (size_t j = 0; j < 100; ++j) {
                std::atomic_ref ref(localCounters[i % 4]);
                ref.fetch_add(1);
            }
        });
    }

    for (auto& thread : threads) {
        thread.join();
    }
}
```