

Query Optimization

Exercise Session 6

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DP_{sub}

- ▶ Iterate over subsets in the integer order
- ▶ Before a join tree for S is generated, all the relevant subsets of S must be available

DPsub

DPsub(R)

Input: a set of relations $R = \{R_1, \dots, R_n\}$ to be joined

Output: an optimal bushy join tree

B = an empty DP table $2^R \rightarrow$ join tree

for each $R_i \in R$

$B[\{R_i\}] = R_i$

for each $1 < i \leq 2^n - 1$ **ascending** {

$S = \{R_j \in R \mid (\lfloor i/2^{j-1} \rfloor \bmod 2) = 1\}$

for each $S_1 \subset S, S_2 = S \setminus S_1$ {

if \neg cross products $\wedge \neg S_1$ connected to S_2 **continue**

$p_1 = B[S_1], p_2 = B[S_2]$

if $p_1 = \epsilon \vee p_2 = \epsilon$ **continue**

$P = \text{CreateJoinTree}(p_1, p_2);$

if $B[S] = \epsilon \vee C(B[S]) > C(P)$ $B[S] = P$

}

}

return $B[\{R_1, \dots, R_n\}]$

Implementation: DPsize

- ▶ dbTable - the vector of lists of Problems, each Problem is either a relation or a join of Problems
- ▶ lookup (hashtable) - mapping the set of the relations to the best solution and its cost
- ▶ initialize dpTable[0] with the list of R_1, \dots, R_n
- ▶ set the size of dpTable to n

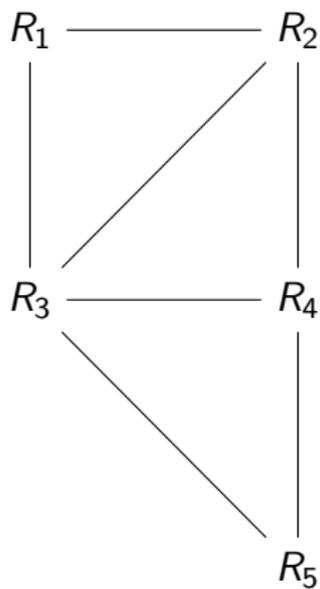
Implementation: DPsize

```
for (i = 1; i < dpTable.size(); i++)
  for (j=0; j < i; j++)
    for (leftRel in dpTable[j])
      for (rightRel in dpTable[i-j-1])
        can we join leftRel and rightRel?
        check lookup for solution and cost
        if the current is cheaper:
          dpTable[i].add(leftRel join rightRel)
          update lookup
```

DPccp

- ▶ Enumerate over all connected subgraphs
- ▶ For each subgraph enumerate all other connected subgraphs that are disjoint but connected to it

Connected Subgraph Enumeration



Connected Subgraph Enumeration

- ▶ Nodes in the query graph are ordered according to a BFS
- ▶ Start with the last node, all the nodes with smaller ID are forbidden
- ▶ At every step: compute neighborhood, get forbidden nodes, enumerate subsets of non-forbidden nodes N
- ▶ Recursive calls for subsets of N

Connected Subgraph Enumeration

EnumerateCsg(G)

for all $i \in [n - 1, \dots, 0]$ **descending** {
 emit $\{v_i\}$;
 EnumerateCsgRec($G, \{v_i\}, B_i$);
}

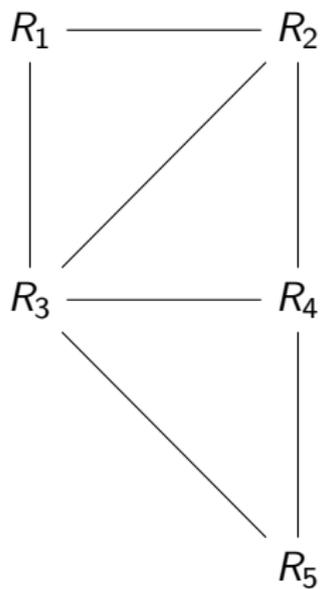
EnumerateCsgRec(G, S, X)

$N = \mathcal{N}(S) \setminus X$;

for all $S' \subseteq N, S' \neq \emptyset$, enumerate subsets first {
 emit $(S \cup S')$;
}

for all $S' \subseteq N, S' \neq \emptyset$, enumerate subsets first {
 EnumerateCsgRec($G, (S \cup S'), (X \cup N)$);
}

Connected Subgraph Enumeration



Enumerating Complementary Subgraphs

EnumerateCmp(G, S_1)

$X = \mathcal{B}_{\min(S_1)} \cup S_1$;

$N = \mathcal{N}(S_1) \setminus X$;

for all ($v_i \in N$ by descending i) {

emit $\{v_i\}$;

 EnumerateCsgRec($G, \{v_i\}, X \cup (\mathcal{B}_i \cap N)$);

}

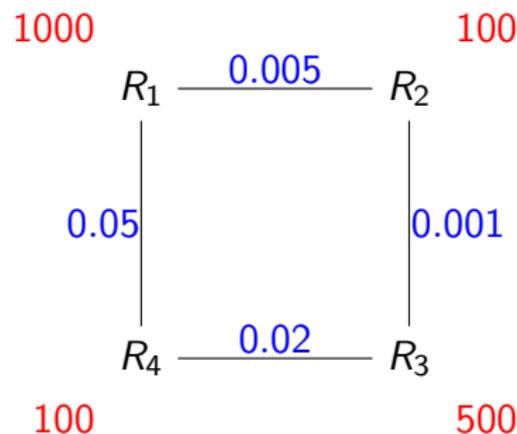
- ▶ EnumerateCsg+EnumerateCmp produce all ccp
- ▶ resulting algorithm DPccp considers exactly $\#ccp$ pairs
- ▶ which is the lower bound for all DP enumeration algorithms

Graph simplification

Sometimes the graph is too big, let's simplify it.

- ▶ GOO: choose the joins greedily (very hard, depends on all other joins)
- ▶ Simplification: choose the joins that must be avoided (we can start with 'obvious' decisions)

Graph simplification: Example



- ▶ $benefit(X \bowtie R_1, X \bowtie R_2) = \frac{C((X \bowtie R_1) \bowtie R_2)}{C((X \bowtie R_2) \bowtie R_1)}$
- ▶ $R_3 \bowtie R_2$ before $R_3 \bowtie R_4$.
Remove $R_4 - R_3$
- ▶ $R_4 \bowtie (R_2 \bowtie R_3)$ before
 $R_4 \bowtie R_1$. Remove $R_1 - R_4$
- ▶ no more choices

$$\begin{aligned} |R_1 \bowtie R_4| &= 5000, & |R_1 \bowtie R_2| &= 500, & |R_2 \bowtie R_3| &= 50, \\ |R_3 \bowtie R_4| &= 1000 \end{aligned}$$

More insights

- ▶ Guido Moerkotte, Thomas Neumann. Analysis of Two Existing and One New Dynamic Programming Algorithm. In VLDB'06
- ▶ Guido Moerkotte, Thomas Neumann. Dynamic Programming Strikes Back. In *SIGMOD'08*
- ▶ Thomas Neumann. Query Simplification: Graceful Degradation for Join-Order Optimization. In *SIGMOD'09*

Homework

- ▶ 3 problems (See website)
- ▶ You will need to revisit some lecture slides for it

Next programming task

- ▶ Due December 8
- ▶ Dynamic Programming (DPsize)
- ▶ We will compare the speed of different submissions :)

Info

- ▶ Exercises due: 9 AM, December 1, 2014