

Query Optimization: Exercise

Session 6

Bernhard Radke

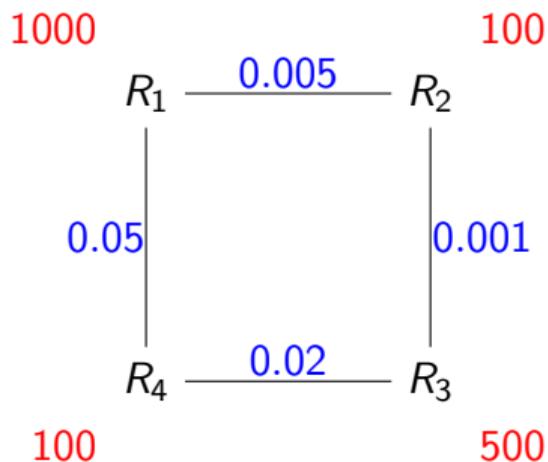
November 26, 2018

Lecture Evaluation

- ▶ Register for the course in TUMonline
- ▶ Evaluation will be done next week in the lecture on December 3
- ▶ Bring your laptop

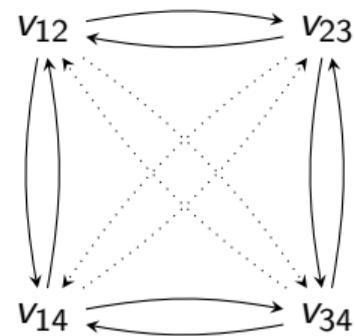
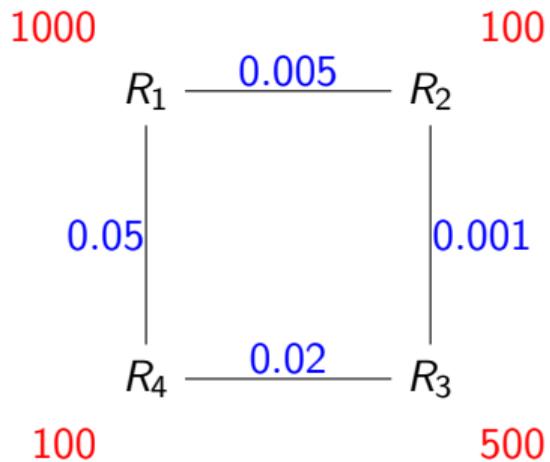
Maximum Value Precedence (MVP) [1]

Weighted Directed Join Graph (WDJG)



Query graph to $WDJG = (V, E_p, E_v)$:

- ▶ nodes $V =$ joins
- ▶ physical edges E_p between "adjacent" joins (share one relation)
- ▶ virtual edges E_v everywhere else
- ▶ $\mathcal{R}(v)$: relations participating in join v
- ▶ Observation: every spanning tree in the WDJG leads to a join tree

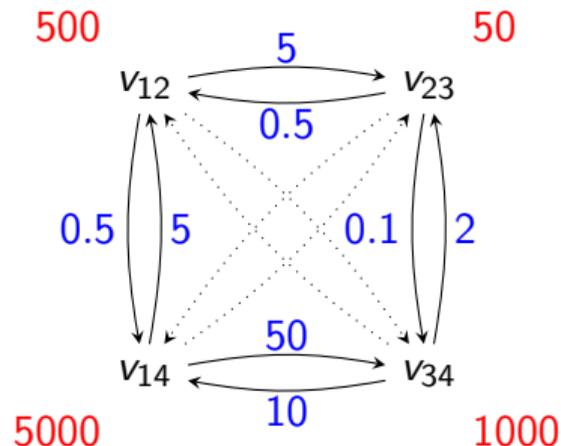


Weights and Costs:

- ▶ edge weights:

$$w_{u,v} = \begin{cases} \frac{|x_u|}{|\mathcal{R}(u) \cap \mathcal{R}(v)|} & \text{if } (u, v) \in E_p \\ 1 & \text{if } (u, v) \in E_v \end{cases}$$

- ▶ node costs: C_{out} of the join



Effective Spanning Tree (EST)

Three conditions:

1. EST is binary
2. For every non-leaf node v_i , for every edge $v_j \rightarrow v_i$ there is a common base relation between v_i and the subtree with the root v_j
3. For every node $v_i = R \bowtie S$ with two incoming edges $v_k \rightarrow v_i$ and $v_j \rightarrow v_i$
 - ▶ R or S can be present at most in one of the subtrees v_k or v_j
 - ▶ unless the subtree v_j (or v_k) contains both R and S

MVP - informally

Construct an EST in two steps:

Step 1 - Choose an edge to reduce the cost of an expensive operation

- ▶ Start with the most expensive node
- ▶ Find the incoming edge that reduces the cost the most
- ▶ Add the edge to the EST and check the conditions
- ▶ Update the WDJG
- ▶ Repeat until
 - ▶ no edges can reduce costs anymore or
 - ▶ no further nodes to consider

Step 2 - Find edges causing minimum increase to the result of joins

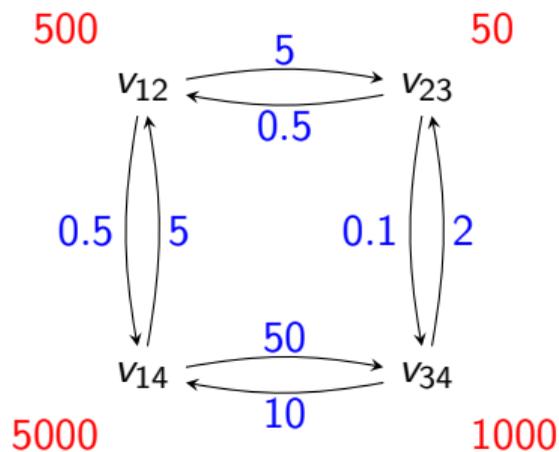
- ▶ Similar to Step 1
- ▶ Start with the cheapest node
- ▶ Find the incoming edge that increases the cost the least

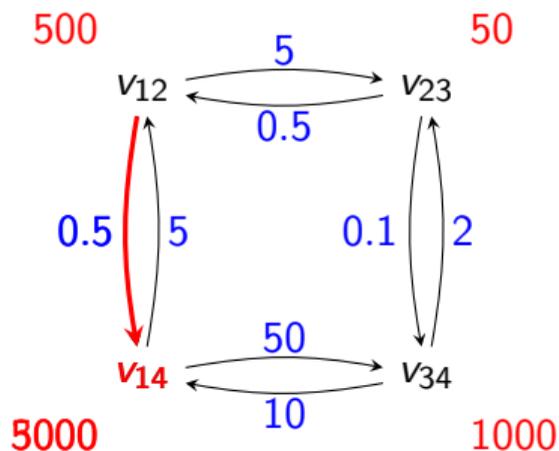
Example

We start with a graph without virtual edges.

Two cost lists:

- ▶ for the Step 1: $Q_1 = v_{14}, v_{34}, v_{12}, v_{23}$
- ▶ for the Step 2: $Q_2 = \emptyset$





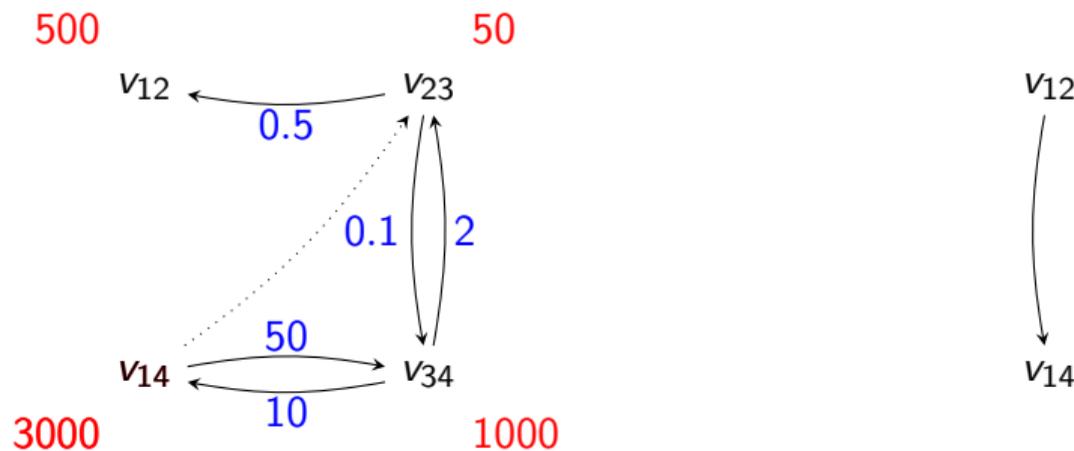
$Q_1 = v_{14}, v_{34}, v_{12}, v_{23}; Q_2 = \emptyset$

Consider v_{14} , select the edge $v_{12} \rightarrow v_{14}$

After v_{12} is executed, $|R_1 \bowtie R_2| = 500$

Replace R_1 by $R_1 \bowtie R_2$ in $v_{14} = R_1 \bowtie R_4$: $v_{14} = (R_1 \bowtie R_2) \bowtie R_4$

$cost(v_{14}) = 500 * 100 * 0.05 + 500 = 3000$



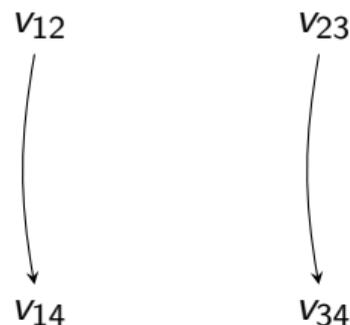
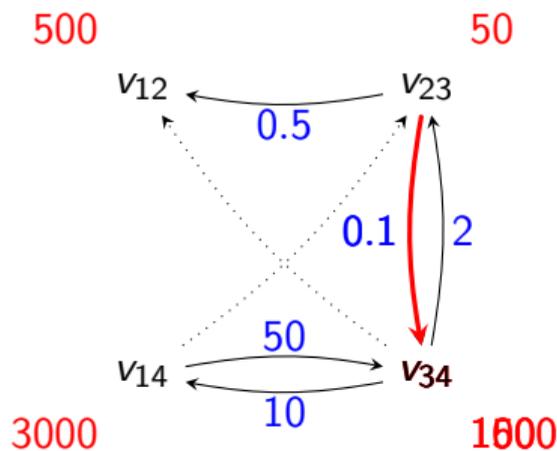
Move $v_{12} \rightarrow v_{14}$ to EST

Update WDJG, remove edges $v_{14} \rightarrow v_{12}$ and $v_{12} \rightarrow v_{23}$, add edge $v_{14} \rightarrow v_{23}$

$Q_1 = v_{14}, v_{34}, v_{12}, v_{23}$; $Q_2 = \emptyset$

Consider v_{14} , no more incoming edges with $w < 1$

$Q_1 = v_{34}, v_{12}, v_{23}$; $Q_2 = v_{14}$



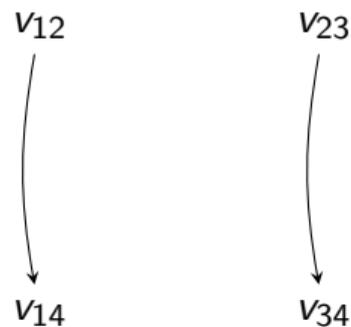
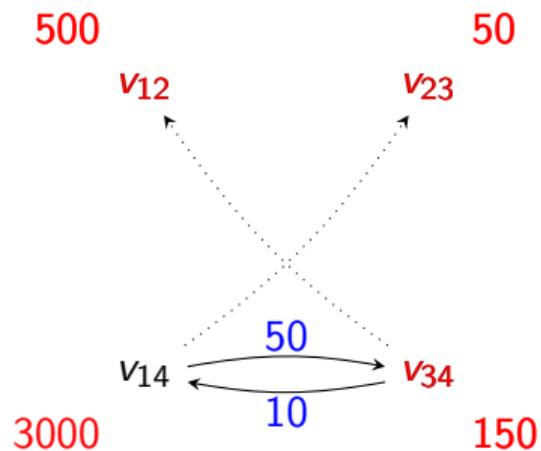
$Q_1 = v_{34}, v_{12}, v_{23}; Q_2 = v_{14}$

Consider v_{34} , select the edge $v_{23} \rightarrow v_{34}$

Recompute cost: $cost(v_{34}) = 50 * 100 * 0.02 + 50 = 150$

Move to EST, Update WDJG

$Q_1 = v_{12}, v_{34}, v_{23}; Q_2 = v_{14}$



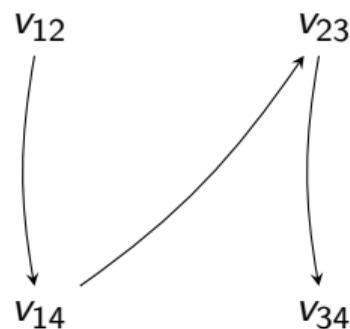
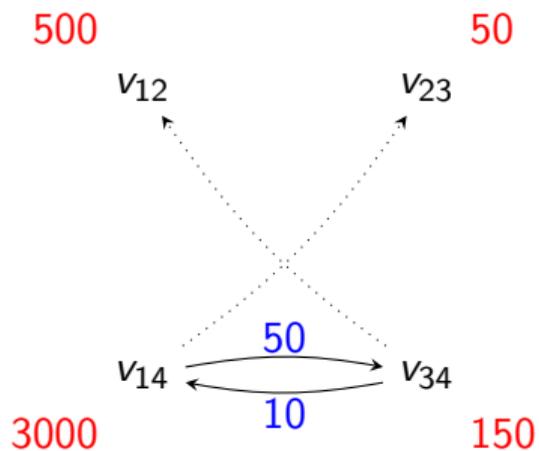
$Q_1 = v_{12}, v_{34}, v_{23}; Q_2 = v_{14}$

Consider v_{12} , no edges

v_{34}, v_{23} : no incoming edges with $w < 1$

$Q_1 = \emptyset; Q_2 = v_{23}, v_{34}, v_{12}, v_{14}$

End of Step 1



$Q_2 = v_{23}, v_{34}, v_{12}, v_{14}$

Consider v_{23} , edge $v_{14} \rightarrow v_{23}$

Adding the edge would not violate EST conditions

Add edge to EST

Done.

Dynamic Programming

Overview

- ▶ generate optimal join trees bottom up
- ▶ start from optimal join trees of size one (relations)
- ▶ build larger join trees by (re-)using optimal solutions for smaller sizes

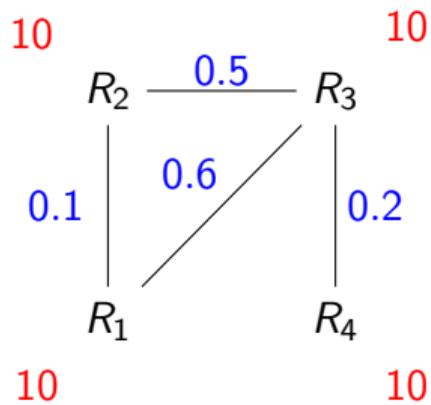
First Approach: DPsizeLinear [2]

- ▶ Enumerate increasing in size
- ▶ Generate linear trees by adding a single relation at a time

Modifications/Extensions:

- ▶ enumerate in integer order
- ▶ generate bushy trees by considering all pairs of subproblems

Example



- ▶ Enumerate connected-subgraph-complement pairs
- ▶ Query Simplification
- ▶ Reordering constraints for non-inner joins

Lecture Evaluation

- ▶ Remember to bring your laptop for the lecture evaluation next week

- ▶ Slides: db.in.tum.de/teaching/ws1819/queryopt
- ▶ Exercise task: [gitlab](#)
- ▶ Questions, Comments, etc:
[mattermost @ mattermost.db.in.tum.de/qo18](https://mattermost.db.in.tum.de/qo18)
- ▶ Exercise due: 9 AM next monday

- [1] C. Lee, C. Shih, and Y. Chen.
Optimizing large join queries using A graph-based approach.
IEEE Trans. Knowl. Data Eng., 13(2):298–315, 2001.
- [2] P. G. Selinger, M. M. Astrahan, D. D. Chamberlin, R. A. Lorie, and T. G. Price.
Access path selection in a relational database management system.
In *Proceedings of the 1979 ACM SIGMOD International Conference on Management of Data, Boston, Massachusetts, May 30 - June 1.*, pages 23–34, 1979.