

# Pipelined Query Execution

Chapter 5



# Database Workloads

- Superscalar CPUs can perform multiple instructions in parallel—if enough *independent* work is available at a time.
- Query-intensive database workloads like decision support, OLAP, data mining, multimedia retrieval require lots of independent calculations.
- Such workloads thus should provide plenty of opportunity to achieve near-optimal CPI ( $< 1$ ).

# TPC-H Query 1

```
SELECT    l_returnflag, l_linestatus,
          sum(l_quantity) AS sum_qty,
          sum(l_extendedprice) AS sum_base_price,
          sum(l_extendedprice * (1 - l_discount))
            AS sum_disc_price,
          sum(l_extendedprice * (1 - l_discount) *
            (1 + l_tax)) AS sum_charge,
          avg(l_quantity) AS avg_qty,
          avg(l_extendedprice) AS avg_price,
          avg(l_discount) AS avg_disc,
          count(*) AS count_order
FROM      lineitem
WHERE     l_shipdate <= date('1998-09-2')
GROUP BY l_returnflag, l_linestatus
```

# High CPI for DBMSs

- Research has shown that DBMSs tend to achieve high CPI (typically  $> 2.5$ ) even on modern CPUs, while SPECint programs achieve  $0.5 < \text{CPI} < 1.5$ .
- Basic architectural principles in DBMS software—e.g., tuple-at-a-time query execution—are to blame.
  - The commonly implemented Volcano iterator model does *not* exhibit sufficient parallelism.

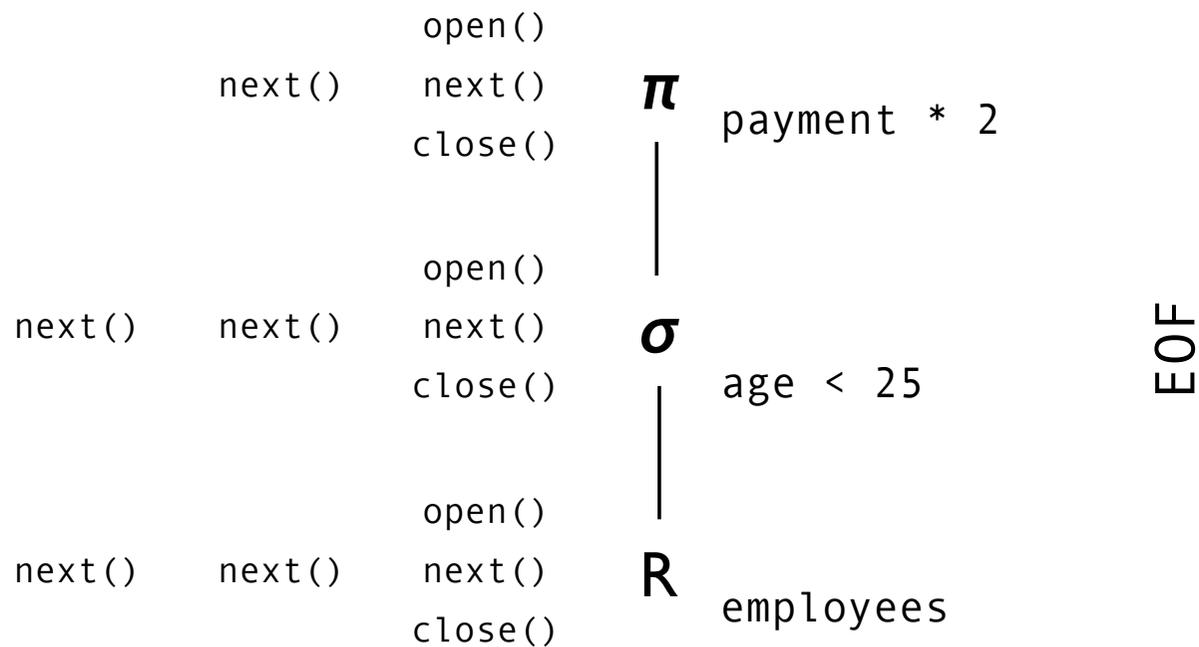
# Volcano Iterator Model

- Each database operator (relational algebra) implements a common interface:

<code>open()</code>	<code>next()</code>	<code>close()</code>
Reset internal state and prepare to deliver first result tuple.	Deliver next result tuple or indicate EOF.	Release internal data structures, locks, etc.

- Evaluation is driven by the top-most operator which receives `open()`, `next()`, `next()`, ... calls and propagates.

# Volcano Iterator Model



# Volcano Iterator Model: Nested-Loops Join

```
join.open() {  
  lhs.open();  
  l = lhs.next();  
  rhs.open();  
}
```

```
join.close() {  
  lhs.close();  
  rhs.close();  
}
```

```
join.next() {  
  do {  
    if (l == EOF) return EOF;  
    r = rhs.next();  
    if (r == EOF) {  
      l = lhs.next();  
      rhs.close();  
      rhs.open();  
      continue;  
    }  
  }  
  while ( $\neg \Theta(l,r)$ );  
  return <l,r>;  
}
```

- **Note: Variable  $l$  is static.**

# Complex Operator Semantics

- Even basic query operators tend to have quite complex semantics.
  - Only at query time  $\text{join}(\text{lhs}, \text{rhs}, \Theta)$  has complete information about relations  $\text{lhs}/\text{rhs}$  and predicate  $\Theta$ , for example:
    - number of columns in  $\text{lhs}/\text{rhs}$ , attribute types, record offsets (*i.e.*, the schema), and an
    - expression interpreter is needed to evaluate  $\Theta$ .

# MySQL gprof Trace

% Time	Calls	# Ins.	IPC	Function
11.9	846M	6	0.64	ut_fold_ulint_pair
8.5	0.15M	27K	0.71	ut_fold_binary
5.8	77M	37	0.85	memcpy
3.1	23M	64	0.88	Item_sum_sum::update_field
3.0	6M	247	0.83	row_search_for_mysql
2.9	17M	79	0.70	Item_sum_avg::update_field
2.6	108M	11	0.60	rec_get_bit_field_1
2.5	6M	213	0.61	row_sel_store_mysql_rec
2.4	48M	25	0.52	rec_get_nth_field
2.4	60	19M	0.69	ha_print_info
2.4	5.9M	195	1.08	end_update
2.1	11M	89	0.98	field_conv
2.0	5.9M	16	0.77	Field_float::val_real
1.8	5.9M	14	1.07	Item_field::val
1.5	42M	17	0.51	row_sel_field_store_in_mysql
1.4	36M	18	0.76	buf_frame_align
1.3	17M	38	0.80	Item_func_mul::val
1.4	25M	25	0.62	pthread_mutex_lock
1.2	206M	2	0.75	hash_get_nth_cell
1.2	25M	21	0.65	mutex_test_and_set
1.0	102M	4	0.62	rec_get_1byte_offs_flag
1.0	53M	9	0.58	rec_1_get_field_start_offs
0.9	42M	11	0.65	rec_get_nth_field_extern_bit
1.0	11M	38	0.80	Item_func_minus::val
0.5	5.9M	38	0.80	Item_func_plus::val

# Tuple-at-a-time Processing

- The  $\text{Item}_*$  operations are invoked by the  $\pi.\text{next}()$  routine (projection), *i.e.*, separately for each tuple.
  - The function call overhead (ca. 20 cycles) must be amortized over only one operation (e.g., addition).
  - The compiler cannot perform loop pipelining. Iteration is “non-local” but *involves all operators* the query tree.

# Full Vertical Fragmentation

C_CUSTKEY	C_NAME	...	C_PHONE
100	Alice		221-921
101	Bob		303-272
102	Carol		555-901

OID	C_CUSTKEY
0@0	100
1@0	101
2@0	102

OID	C_NAME
0@0	Alice
1@0	Bob
2@0	Carol

OID	C_PHONE
0@0	221-921
1@0	303-272
2@0	555-901

# Binary Association Tables (BATs)

BAT [*oid*, *t*]

head	tail
0@0	<i>a</i>
1@0	<i>b</i>
2@0	<i>c</i>
3@0	<i>d</i>
4@0	<i>e</i>
5@0	<i>f</i>

head	tail
0@0	<i>a</i>
1@0	<i>b</i>
2@0	<i>c</i>
3@0	<i>d</i>
4@0	<i>e</i>
5@0	<i>f</i>

- Typically, column head contains dense, ascending OIDs (integers).
- BATs degenerate to 1-dim arrays.
- Positional lookups (offset-based).

# BAT Algebra:

## Fixed Schema, Less Freedom

- Equi-join between two BATs:

`join(BAT[t1, t2], BAT[t2, t3]) : BAT[t1, t3]`

- Schema of input and output relations is fixed.
- No predicate interpreter required.
- Complex expressions, e.g., `extprice * (1 - tax)`:

```
tmp1 := [-](1, tax);  
tmp2 := [*](extprice, tmp1);
```

# Column-at-a-Time Processing and Pipelining

- The column-at-a-time operators perform many simple operations in a tight loop. Loop unrolling and pipelining is applicable. Implementation of [-]:

```
map_sub_double_val_double_col(  
    int n,  
    double c,  
    double* __restrict__ res,  
    double* __restrict__ col1)  
{  
    for (int i=0; i<n; i++)  
        res[i] = c - col1[i];  
}
```

# TPC-H Query 1 Experiments

- Query execution time for TPC-H scale factor SF = 1 (6M rows in table lineitem) AthlonMP @1.5 GHz:

MySQL 4.1	MonetDB/ MIL	Hand- coded C
28.1 s	3.7 s	0.22 s

- The “ultra-tight” loops in MonetDB suffer from memory bandwidth limits (ca. 500 MB/s, see upcoming chapters).

```

void tpch_query1(
    int n, int hi_date,
    unsigned char* __restrict__ l_returnflag,
    unsigned char* __restrict__ l_linestatus,
    double* __restrict__ l_quantity,
    double* __restrict__ l_extendedprice,
    double* __restrict__ l_discount,
    double* __restrict__ l_tax,
    int* __restrict__ l_shipdate,
    aggr_t1* __restrict__ hashtab)
{
    for (int i=0; i<n; i++) {
        if (l_shipdate[i] <= hi_date) {
            aggr_t1 *entry = hashtab +
                (l_returnflag[i] << 8) + l_linestatus[i];
            double discount = l_discount[i];
            double extprice = l_extendedprice[i];
            entry->count++;
            entry->sum_qty += l_quantity[i];
            entry->sum_disc += discount;
            entry->sum_base_price += extprice;
            entry->sum_disc_price += (extprice * (1 - discount));
            entry->sum_charge += extprice * (1 - l_tax[i]);
        }
    }
}

```

# MonetDB/X100

- MonetDB/X100, developed at CWI, Amsterdam. Principal architect is Peter Boncz.

<http://homepages.cwi.nl/~boncz/x100.html>

- MonetDB/X100 applies full vertical fragmentation internally (column storage).
- Columns are processed in chunks (vectors) using Volcano-style iteration. MonetDB/X100 takes care to ensure that all live vectors fit in the CPU cache.

# MonetDB/X100 Algebra

- Operates over  $n$ -ary tables. Internally: column storage.
- Table: materialized table, Dataflow: pipelined vectors (typical vector size:  $2^{10}$  values, adaptable to cache size)

---

Table(ID):Table

---

Scan(Table):Dataflow

---

Project(Dataflow,List<Exp<\*>>):Dataflow

---

Aggr(Dataflow,List<Exp<\*>>,List<Aggregates>):Dataflow

---

Select(Dataflow,Exp<bool>):Dataflow

---

# Selection Vectors

	A
0	10
1	5
2	42
3	35
4	6
5	16

Select( $\cdot$ , A > 10)

pos
2
3
5

- No data is copied from the selection source—saves memory traffic if source column is wide.
- Other MonetDB/X100 algebra operators need to be aware of selection vectors.

# Highly Specialized Primitives

```
map_plus_double_col_double_col(  
    int n,  
    double* __restrict__ res,  
    double* __restrict__ col1,  
    double* __restrict__ col2,  
    int *__restrict__ sel)  
{  
    if (sel) {  
        for (int j=0; j<n; j++) {  
            int i = sel[j];  
            res[i] = col1[i] + col2[i];  
        }  
    } else {  
        for (int i=0; i<n; i++)  
            res[i] = col1[i] + col2[i];  
    }  
}
```

- Uses ca. 2 cycles/tuple (MySQL: 49 cycles).

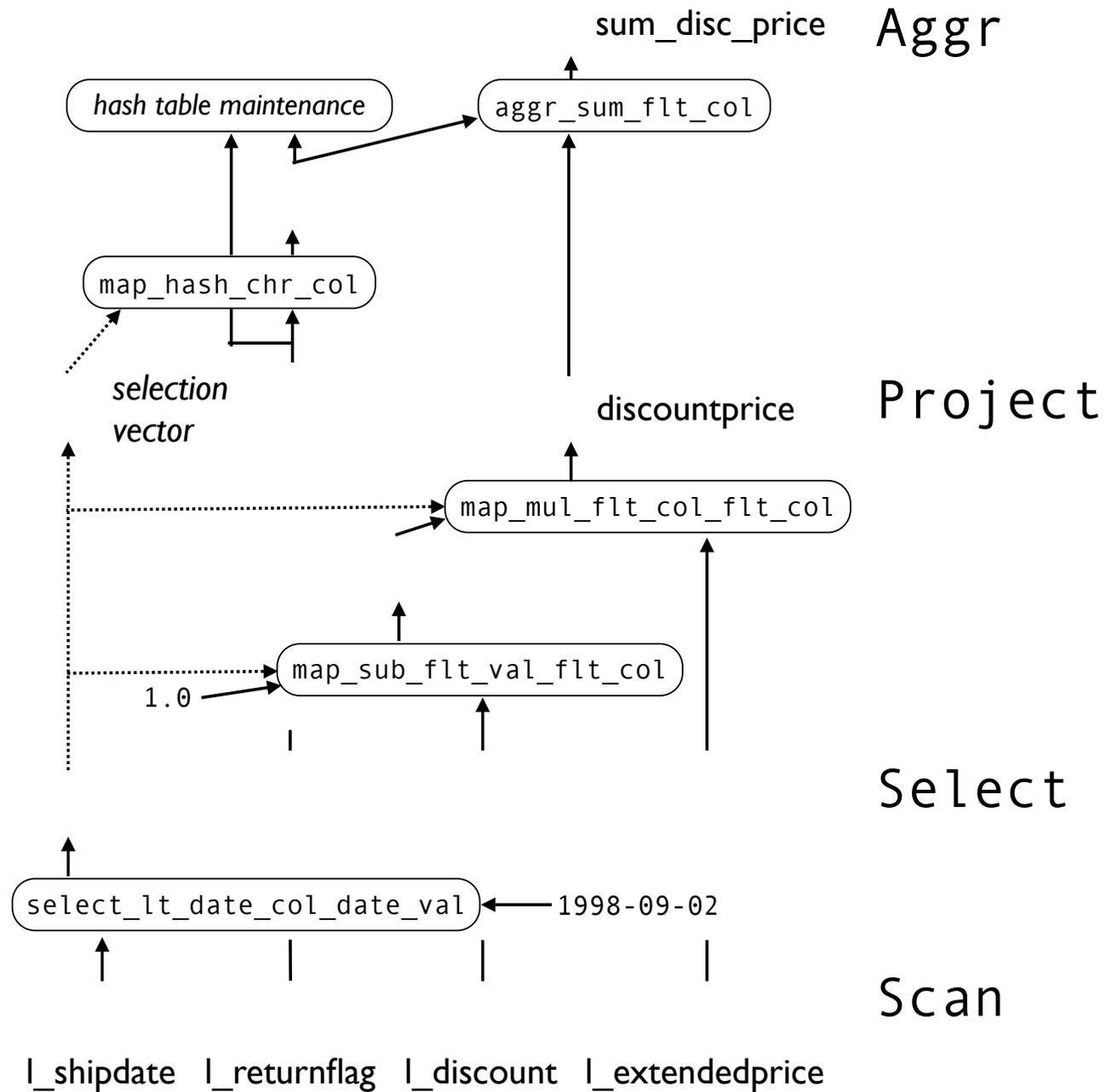
# Simplified TPC-H Query 1

SQL

```
SELECT    sum(l_extendedprice * (1 - l_discount))
          AS sum_disc_price
FROM      lineitem
WHERE     l_shipdate < date("1998-09-02")
GROUP BY l_returnflag
```

X100 Algebra

```
Aggr (
  Project (
    Select (
      Scan (Table (lineitem)),
      < (l_shipdate, date("1998-09-02"))),
      [ discountprice = * (- (1.0, l_discount),
                          l_extendedprice) ] ) ,
    [ returnflag ],
    [ sum_disc_price = sum(discountprice) ])
```

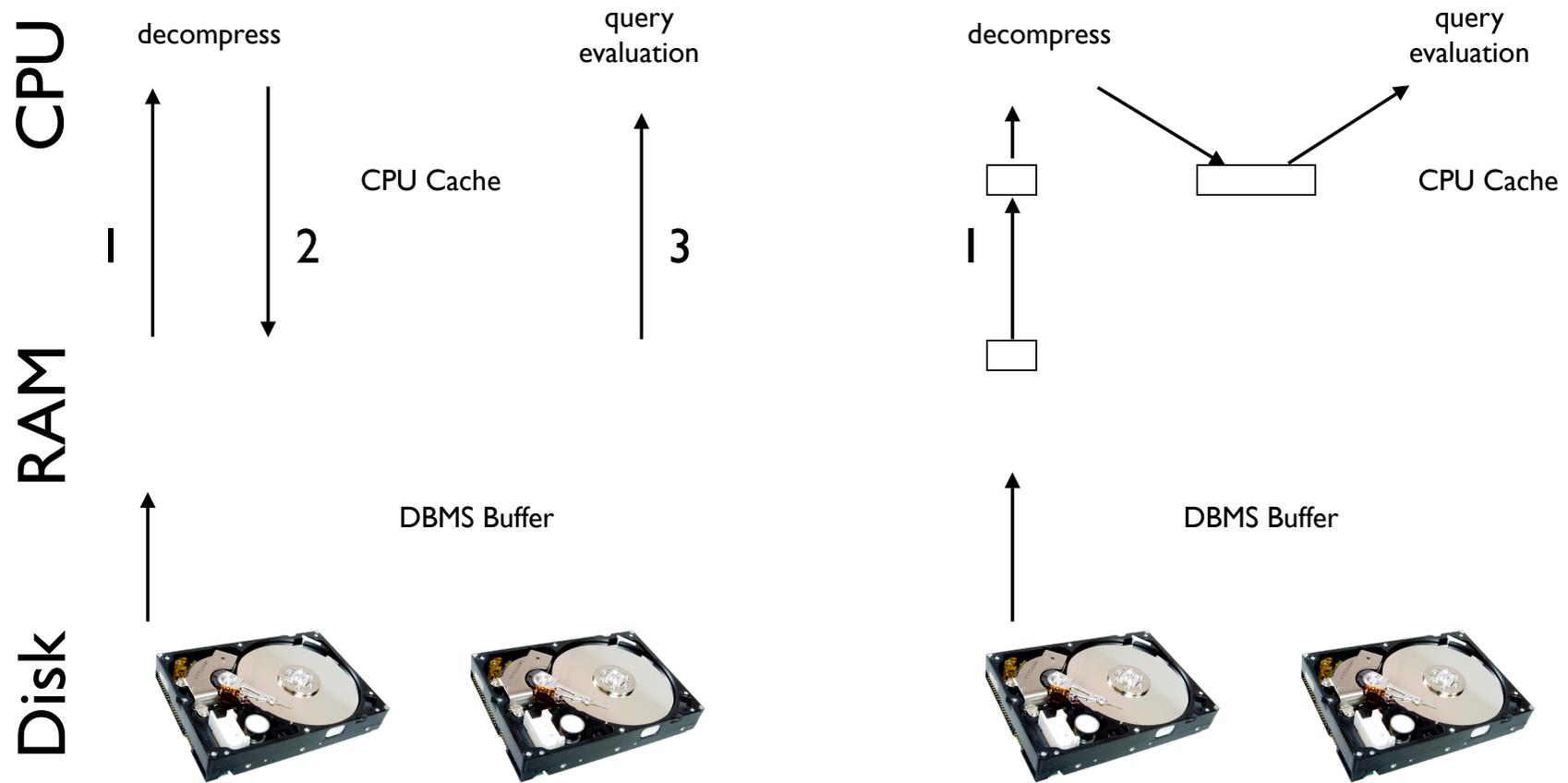


# Pipelined Query Evaluation and I/O Hunger

- Vector-based pipelineable query execution leads to extremely high tuple bandwidth figures.
  - If vectors are cache-resident, bandwidths of multiple GB/s are achieved (e.g., 5 GB/s for `map_mult_*` on an Athlon MP @ 1.5 GHz).
  - Modern, high-end RAID systems can only deliver  $\approx 0.3$  GB/s — Are we hopelessly I/O bound?
- $\Rightarrow$  Maintain compressed data on disk and RAM.



# Disk-RAM vs. RAM-CPU Compression



# RAM–CPU Compression

- Avoids to cross the CPU/RAM border 3 times.
  - DBMS buffer manager stores compressed pages and thus can cache more data.
  - Decompress at small granularity ( $<$  CPU cache size) and just when the query processor requests it.
  - Requires high-bandwidth, lightweight compression schemes.

# Decompression Speed

- Bandwidth of generic decompression algorithms will *not* be sufficient:

bzip2	zlib
10 MB/s	80 MB/s

- Modern RAID systems deliver 0.3 GB/s.
- Assume compression ratio of 4:1— decompression will need to sustain a bandwidth of 1.2 GB/s.
- Invest about 40% of CPU time into decompression: decompression needs to deliver 3 GB/s.

# Lightweight Compression: FOR

- Frame of reference (FOR) compressor:
  - Block-wise compression, values  $C[i]$ . Let  $min_C$  denote the minimum  $C$  value in the block.
  - In the compressed block, store  $(C[i] - min_C)$  values with fixed bit length.
- Requires  $\lceil \log_2(max_C - min_C + 1) \rceil$  bits per value.

Works well with clustered data. Also used to compress pointers in B-tree indexes.

# Lightweight Compression: DICT

- Dictionary compression (DICT, *enumerated storage*) exploits value distributions which use a small subset of a full domain (= value range admitted by a type).
- Encode values by a code with minimal bit length:

Gender
“female”
“female”
“male”
“female”
“male”

Gender
0
0
1
0
1

+

Code	Dict
0	“female”
1	“male”

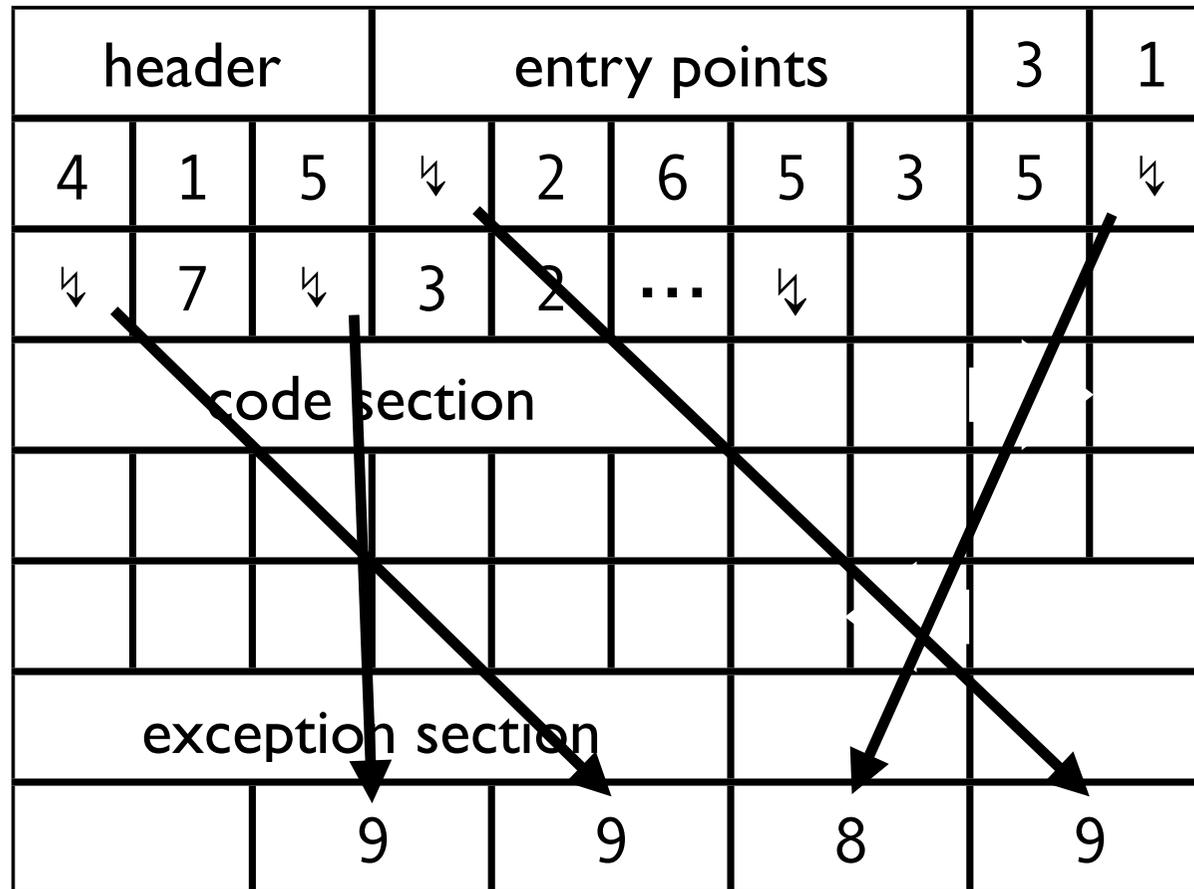
# Skewed Data and Outliers



- FOR and DICT are vulnerable to outliers and skew:
  - FOR suffers from extreme  $max_C, min_C$  values.
  - DICT needs  $\lceil \log_2(|Dictionary|) \rceil$  bits and thus also suffers from skew and outliers.
- Treat outliers as exceptions which do not influence  $max_C, min_C$  or the dictionary size, respectively. Requires exception handling.

# Block Layout (3-Bit Code):

## 3.1415926535897932



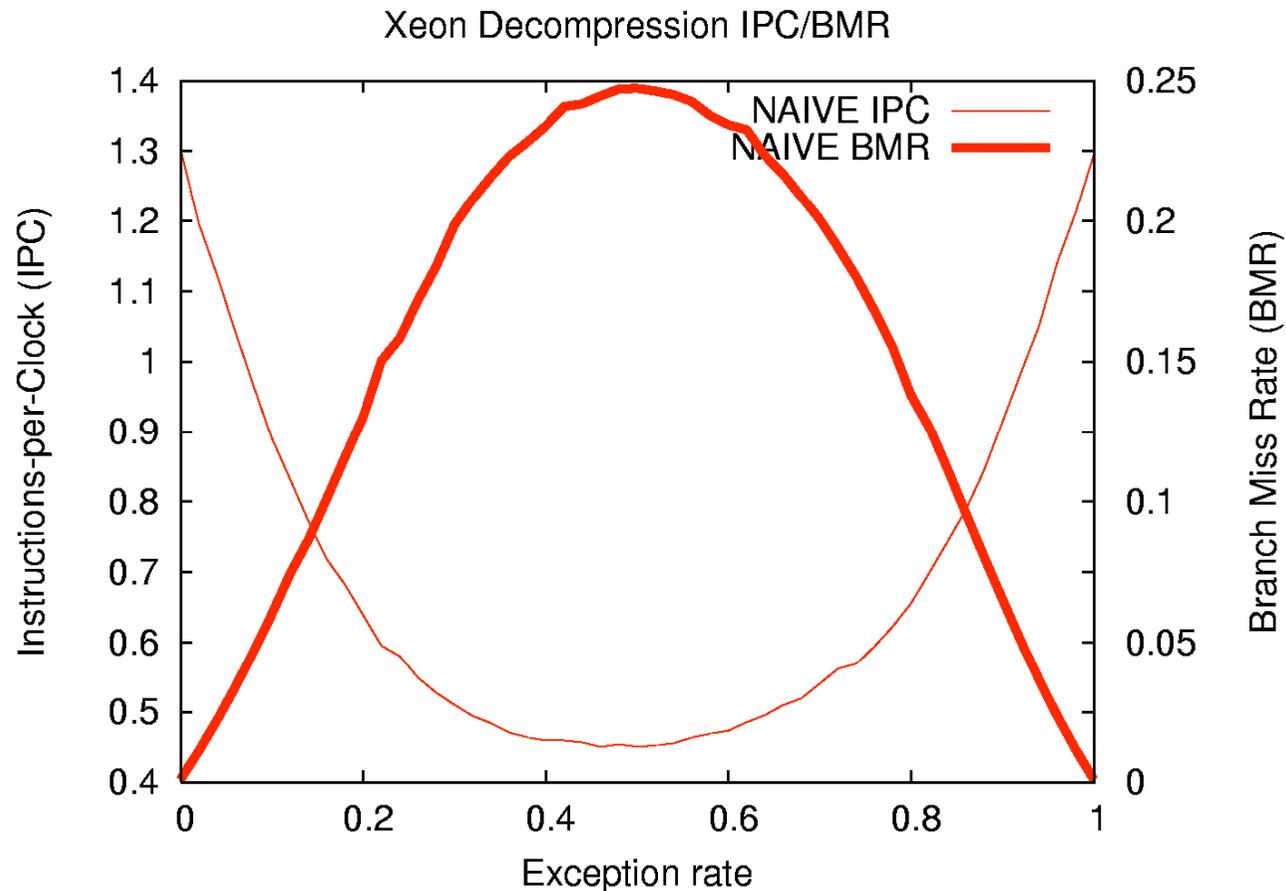
# Naïve Decompression

```
int i;      /* points into codes */
int j = 0;  /* points into exceptions */

for (i = 0; i < n; i++) {
    if (code[i] != ↴)
        output[i] = DECODE(code[i]);
    else
        output[i] = exception[--j]);
}
```

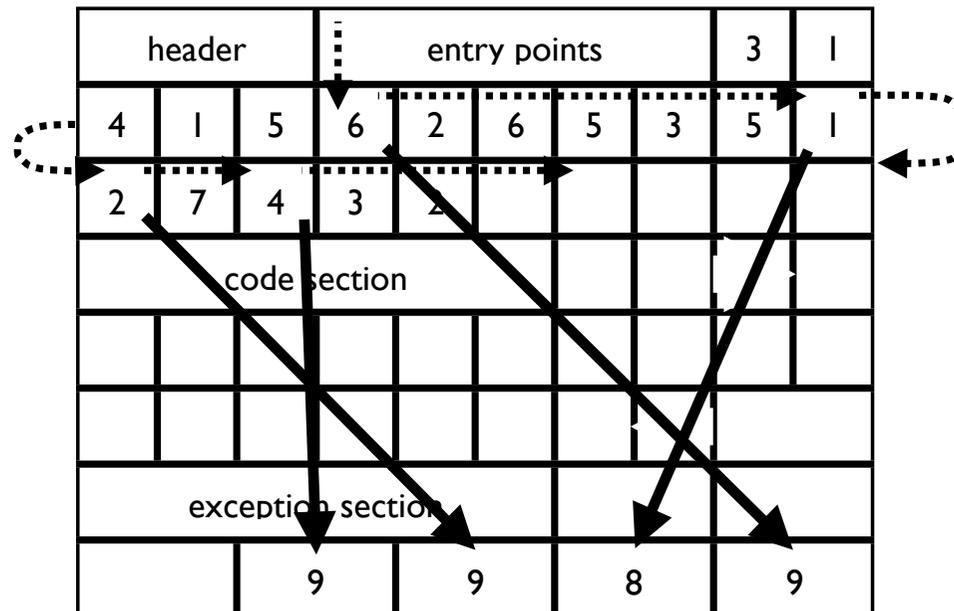
- Assume  $b$ -bit codes to have been unpacked into array `code[]` (negligible effort).
- Function `DECODE()` implements FOR (DICT) decompression.
- Misprediction rate depends on exception ratio.

# Naïve Decompression on an Intel Xeon<sup>®</sup> CPU



# Patch Lists

- Maintain a patch list through code word section that links exceptions:
  1. Decode all codes, *including* patch markers.
  2. Patch up the exception positions.



# Decompression with Patches

```
void decompress (  
    int n;  
    int* __restrict__ output,  
    int* __restrict__ code,      /* points to code section */  
    int* __restrict__ exception, /* points after exceptions */  
    int  entry_point            /* first exception */  
)  
{  
    /* phase 1: decode regardless */  
    for (int i=0; i < n; i++)  
        output[i] = DECODE(code[i]);  
  
    /* phase 2: patch up */  
    for (int i=1; entry_point < n; i++) {  
        output[entry_point] = exception[-i];  
        entry_point += code[entry_point]; /* walk patch list */  
    }  
}
```

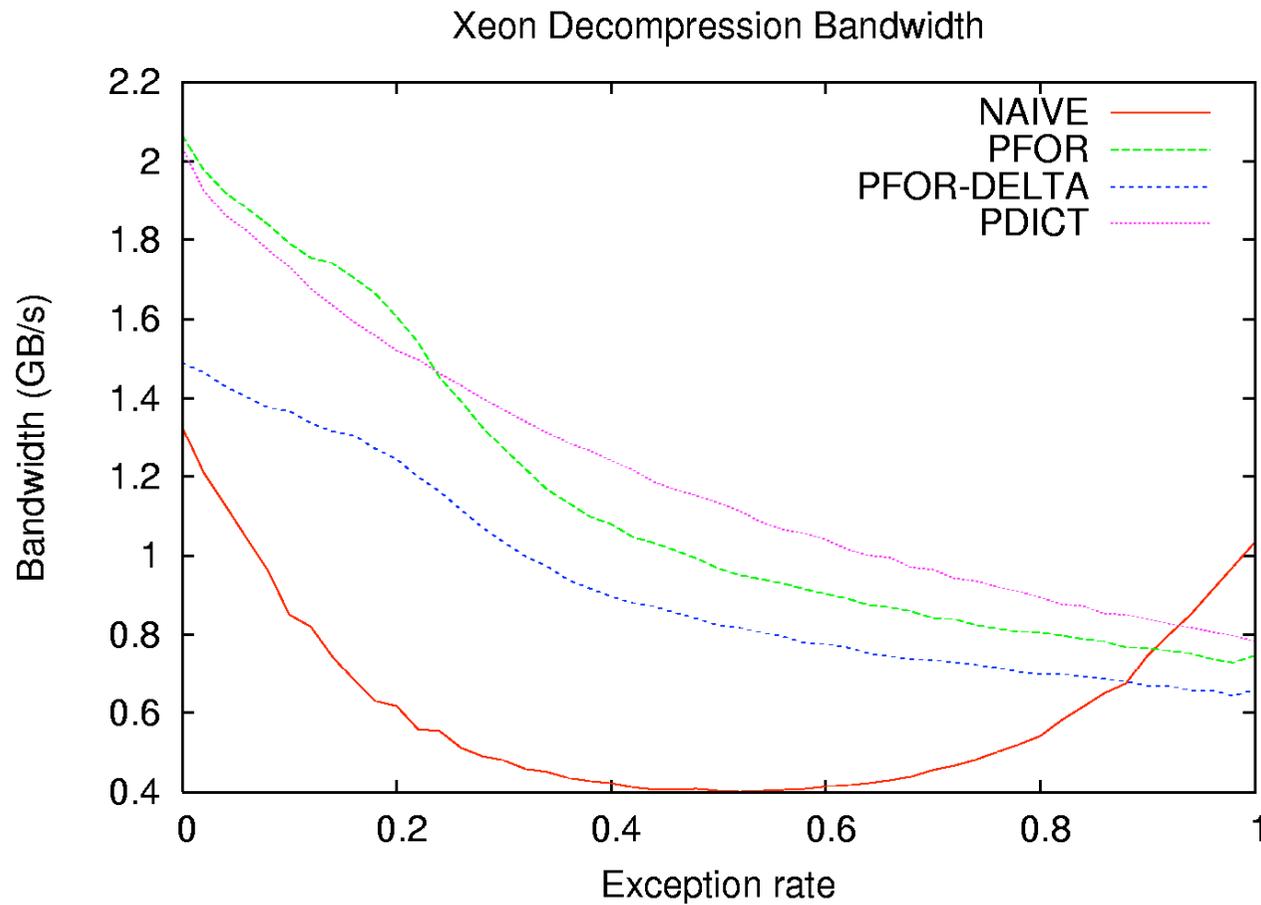
# Control Dependence to Data Dependence

- Note the data dependency in the patch loop:

```
/* phase 2: patch up */  
for (int i=1; entry_point < n; i++) {  
    output[entry_point] = exception[-i];  
    entry_point += code[entry_point]; /* walk patch list */  
}
```

- This dependency is inherent to *any* list walking strategy.
- Data hazards are less costly than control hazards. Patch loop processes small percentage of data only.

# Decompression Bandwidth



# Compression with Patching

```
void compress (
    int n;
    int* __restrict__ input,
    int* __restrict__ code,      /* points to code section */
    int* __restrict__ exception, /* points after exceptions */
    int* last_patch             /* position of last patch */ )
{
    int miss[N], nexc;

    for (int i = 0, nexc = 0; i < n; i++) {
        int c = ENCODE(input[i]);
        code[i] = c;
        miss[nexc] = i;
        nexc += (c > MAXCODE);      /* MAXCODE = 2b-1 */
    }
    for (int i = 0; i < nexc; i++) {
        int patch = miss[i];
        exception[-i] = input[patch];
        code[*last_patch] = patch - *last_patch;
        *last_patch = patch;
    }
}
```

# Compiling Selection Conditions

- Column-at-a-time selections repeatedly evaluate a given (compound) predicate in a tight inner loop.
- Consider

$$\sigma_{p1 \wedge p2 \wedge p3}(q)$$

in which we assume predicate  $p_i$  to be evaluated on column  $col_i$  of the input query  $q$ .

# Compiling Selection Conditions

```
int j = 0;

for (int i = 0; i < n; i++) {
    if (p1(col1[i]) && p2(col2[i]) && p3(col3[i]))
        res[j++] = i;
}
```

- In C, && is also known as the *branching and* operator:

```
if (p && q) {
    s;
}
```

compile

```
...           ; evaluate p (→ R1)
BEQZ R1,skip
...           ; evaluate q (→ R2)
BEQZ R2,skip
s;           ; code for s
skip: ...
```

# Compiling Selection Conditions

```
int j = 0;

for (int i = 0; i < n; i++) {
    if (p1(col1[i]) & p2(col2[i]) & p3(col3[i]))
        res[j++] = i;
}
```

- Operator `&` performs *bitwise and* (no shortcut eval):

```
if (p & q) {
    s;
}
```

compile

```
...           ; evaluate p (→ R1)
...           ; evaluate q (→ R2)
AND   R3,R1,R2
BEQZ  R3,skip
s;           ; code for s
skip: ...
```

# Compiling Selection Conditions

```
int j = 0;

for (int i = 0; i < n; i++) {
    res[j] = i;
    j += (p1(col1[i]) & p2(col2[i]) & p3(col3[i]))
}
```

- In C, Booleans are represented as 0 (*false*) or 1 (*true*):

```
j += p & q;
```

compile

```
...           ; evaluate p (→ R1)
...           ; evaluate q (→ R2)
AND  R3,R1,R2
ADD  R4,R4,R3           ; j ≡ R4
```

# Need Cost Model to Select Between Variants

- $p \ \&\& \ q$ :  
When  $p$  is highly selective this might amortize the double branch misprediction risk.
- $p \ \& \ q$ :  
Number of branches halved but  $q$  is evaluated regardless of  $p$ 's outcome.
- $j \ += \ \dots$ :  
Performs memory write in *each* iteration.



# Mixed-Mode Selection

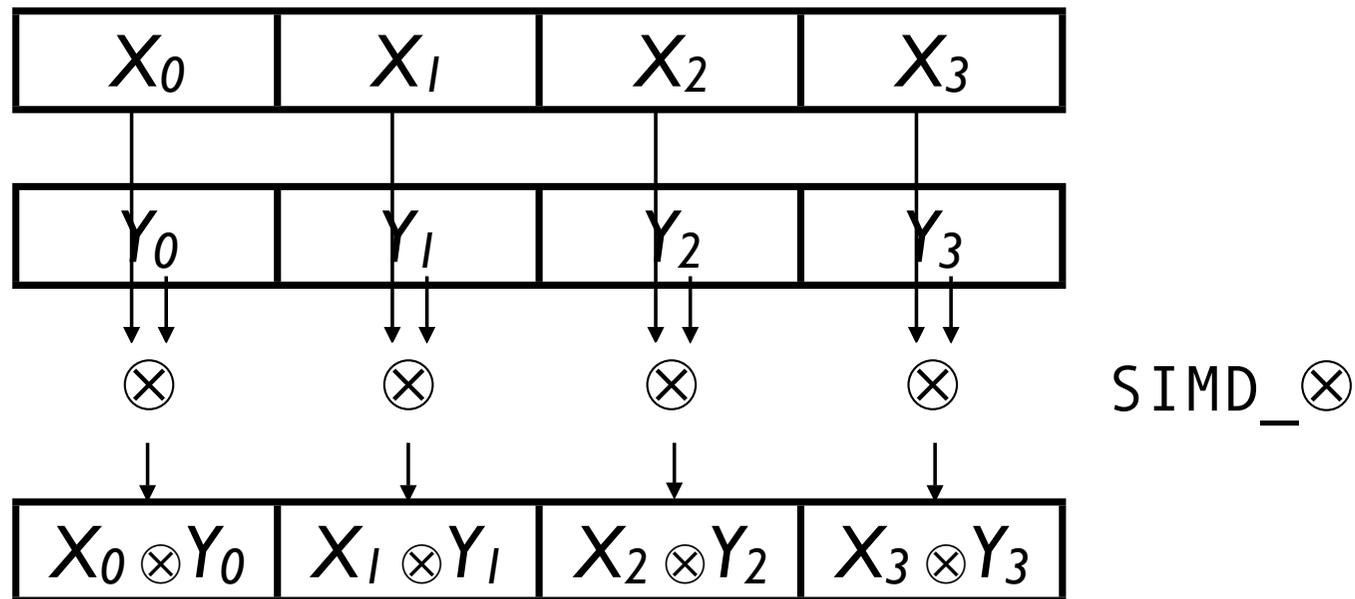
```
int j = 0;

for (int i = 0; i < n; i++) {
    if (p1(col1[i]) & p2(col2[i]) && p3(col3[i])) {
        res[j] = i;
        j += p4(col3[i])
    }
}
```

- **Problem:**  
Programming language compiler would need information about database-level meta-data (e.g., selectivities) to make informed choice.
- **Enable runtime choice:** compile specialized variants, dynamic compilation and linking, self-modifying code.

# Exploiting SIMD Operations

- SIMD (single instruction, multiple data) instructions have primarily been added to modern CPUs to accelerate multi-media operations:



# SIMD Intrinsics

- Ideally, a programming language compiler would automatically detect opportunities to exploit SIMD instructions (e.g., after loop unrolling).
  - Today's compilers still miss too many (non-)obvious opportunities  $\Rightarrow$  use explicit SIMD intrinsics:  
`SIMD_<`, `SIMD_AND`, `SIMD_+`, ...
- Here: use Pentium4 SSE SIMD intrinsics, 128-bit SIMD registers. Pack  $S = 4$  32-bit FP values into SIMD reg.

# SIMD: Scan-Like Operations

- High-level structure (assume  $N \bmod S = 0$ ):

```
for (i = 1; i <= N; i++) {  
    if ( $\Theta(x[i])$ )  
        process1(y[i]);  
    else  
        process2(y[i]);  
}
```

- High-level structure after introduction of SIMD intrinsics (`SIMD_Process()` needs to be adapted):

```
for (i = 1; i <= N; i += S) {  
    mask[1..S] = SIMD_  $\Theta(x[i..i+S-1])$ ;  
    SIMD_Process(mask[1..S], y[i..i+S-1]);  
}
```

# Return First Match

```
for (i = 1; i <= N; i++) {  
    if ( $\Theta(x[i])$ )  
        process1(y[i]);  
    else  
        process2(y[i]);  
}
```

```
for (i = 1; i <= N; i++) {  
    if ( $\Theta(x[i])$ )  
        { result = y[i]; return; }  
    else  
        ;  
}
```

```
SIMD_Process(mask[1..S], y[1..S])  
{  
    int V = SIMD_bit_vector(mask);    /*  $V \in [0, 2^S - 1]$  */  
    if (V != 0) {  
        for (int j = 1; j <= S; j++)  
            if ((V >> (S - j) & 1) {  
                result = y[j];  
                return;  
            }  
    }  
}
```

# Return All Matches

```
for (i = 1; i <= N; i++) {  
    if ( $\Theta(x[i])$ )  
        process1(y[i]);  
    else  
        process2(y[i]);  
}
```

```
for (i = 1; i <= N; i++) {  
    if ( $\Theta(x[i])$ )  
        { result[pos++] = y[i]; }  
    else  
        ;  
}
```

```
SIMD_Process(mask[1..S], y[1..S])  
{  
    int V = SIMD_bit_vector(mask);    /*  $V \in [0, 2^S - 1]$  */  
    if (V != 0) {  
        for (int j = 1; j <= S; j++) {  
            int match = (V >> (S - j)) & 1;  
            result[pos] = y[j];  
            pos += match;  
        }  
    }  
}
```

# Aggregation (SUM)

```
SELECT  SUM(R.y)
FROM    R
WHERE    $\Theta$ (R.x)
```

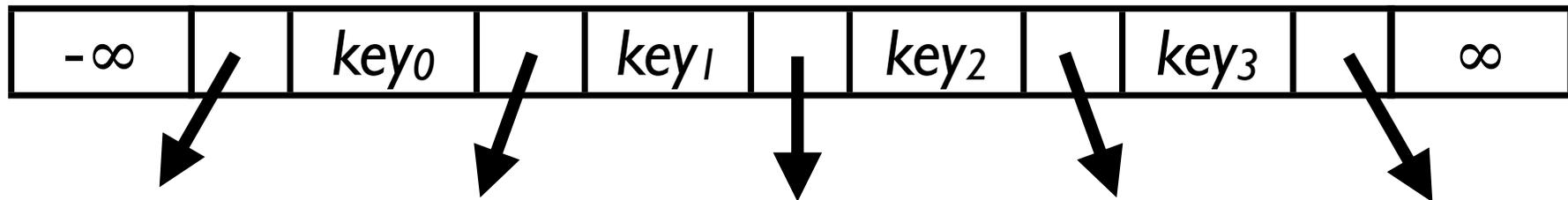
```
for (i = 1; i <= N; i++) {
    if ( $\Theta$ (x[i]))
        { result += y[i]; }
    else
        ;
}
```

```
SIMD_Process(mask[1..S], y[1..S])
{
    sum[1..S] = SIMD_+(sum[1..S],
                      SIMD_AND(mask[1..s], y[1..S]));
}
```

- Finally, sum up the  $S$  32-bit words in  $\text{sum}[1..S]$ .

# Search in Internal B+-Tree Nodes

$$key_2 \leq K < key_3$$



- Common implementation in DBMS:  
Perform *binary search* (search key  $K$ ) among B+-tree node keys. Determine *branch number* (here: 3).
- B+-tree implementations strive for high fan-out.

# Binary Search and Branch Prediction

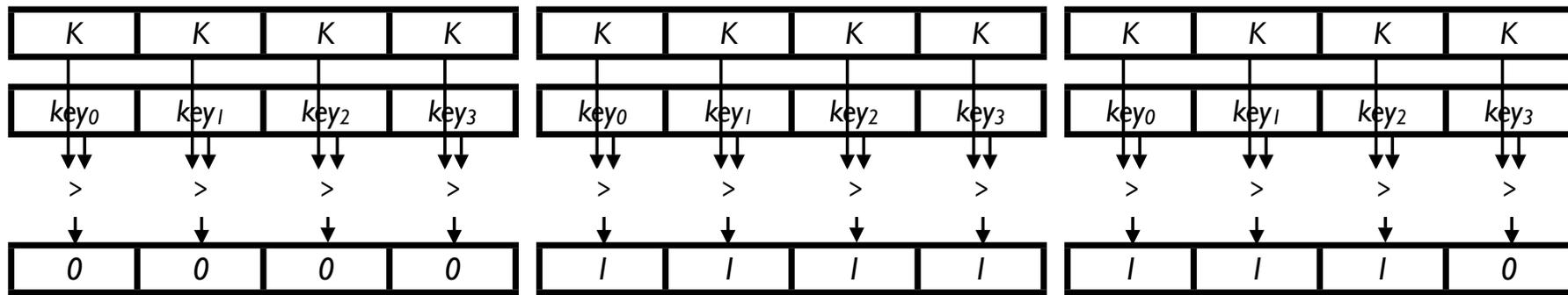


```
int bin_search(
    double* key,
    double K,
    int l, r)
{
    int mid = (l + r) / 2;

    if (key[mid] <= K && K < key[mid+1])
        return mid;
    if (K >= key[mid+1])
        return bin_search(key, K, mid+1, r);
    /* K < key[mid] */
    return bin_search(key, K, l, mid);
}
```

- Branch guides the search and will be unpredictable.

# SIMD in Binary Search

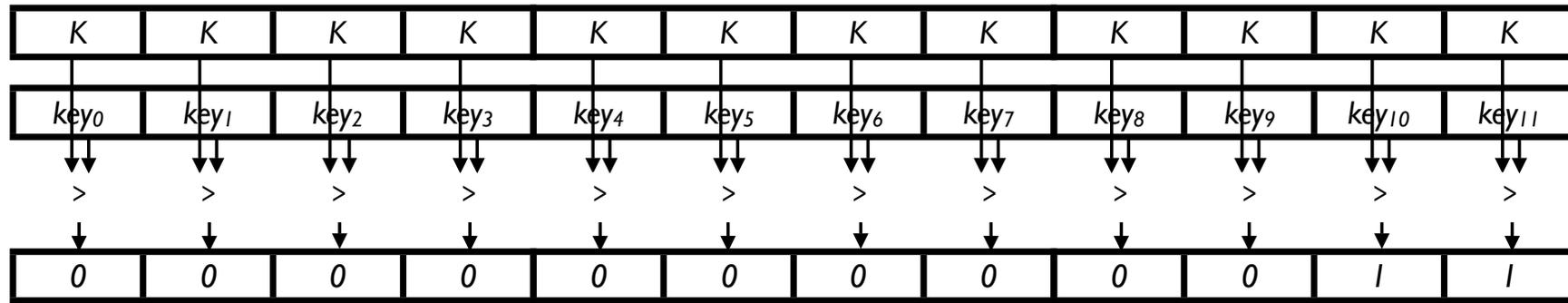


search among  
keys smaller than  
*key<sub>0</sub>* (left)

search among  
keys larger than  
*key<sub>3</sub>* (right)

key found, SIMD  
mask indicates  
branch number

# SIMD in Sequential Search



- Search *sequentially*, left to right.  
Branch number  $\equiv$  # of 0 bits in the SIMD masks.
- Avoids (almost all) branches during the search but touches about 50% of all key values in B+-tree node.