

# In-Database Machine Learning with SQL on GPUs

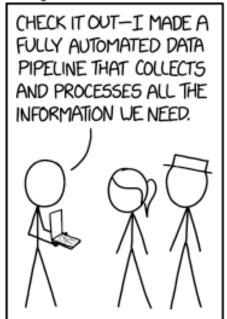
Maximilian E. Schüle, Harald Lang, Maximilian Springer, Alfons Kemper, Thomas Neumann, Stephan Günnemann Tampa, Florida, USA, July 6-7, 2021

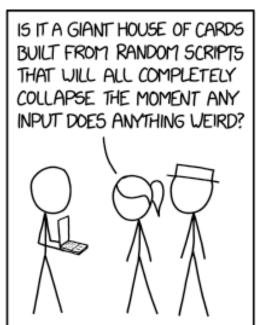




## In-Database Machine Learning: Problem

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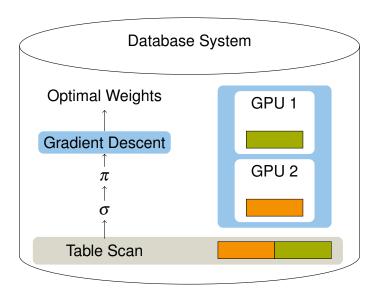


## In-Database Machine Learning: Solution





## In-Database Machine Learning



- SQL sufficient for machine learning (ML)
  - Turing-complete with recursive tables
  - Streams for continuous learning
  - Sample operator for stochastic gradient descent
- Idea
  - Data preprocessing using SQL
  - No need for data extraction out of a database system
  - Continuously train models using operators for gradient descent with GPU support
  - Label data within the database system using SQL



## Structure







ML in SQL-92 Gradient descent with recursive tables

Machine learning pipeline in SQL

**ML Operators Automatic Differentiation Gradient Descent Operator** 

**GPU** support GPU co-processing Evaluation





## ML in SQL-92





## ML in SQL-92: Gradient Descent with Recursive SQL

A *loss function*  $I_{X,y}(\vec{w})$  measures the deviation (*residual*) between all approximated values  $m_{\vec{w}}(X)$  and the given labels  $\vec{y}$ , for example, mean squared error:

$$I_{x,y}(a,b) = (a \cdot x + b - y)^2$$
 (1)

$$\nabla I_{x,y}(a,b) = \begin{pmatrix} \partial I/\partial a \\ \partial I/\partial b \end{pmatrix} = \begin{pmatrix} 2(ax+b-y) \cdot x \\ 2(ax+b-y) \end{pmatrix}. \tag{2}$$

To minimise  $I_{X,y}(\vec{w})$ , gradient descent updates the weights per iteration by subtracting the loss function's gradient times the learning rate  $\gamma$ .

$$\vec{\mathbf{w}}_{t+1} = \vec{\mathbf{w}}_t - \gamma \nabla I_{X,\vec{\mathbf{y}}}(\vec{\mathbf{w}}_t), \tag{3}$$

$$\vec{\mathbf{w}}_{\infty} pprox \lim_{t \to \infty} \vec{\mathbf{w}}_t.$$
 (4)

```
create table data (x float, y float);
insert into data ...

with recursive gd (id, a, b) as (
    select 0,1::float,1::float
UNION ALL
    select id+1,
        a-0.05*avg(2*x*(a*x+b-y)),
        b-0.05*avg(2*(a*x+b-y))
    from gd, (select * from data )
    where id<5 group by id,a,b)
    select * from gd order by id;
        Listing 1: Gradient descent (batch).</pre>
```

Five iterations, loss function with two weights (8). First, the weights get initialised, then each iteration updates the weights (3) based on manually derived gradients (2) and  $\gamma = 0.05$ .



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    select id+1,
        a-0.05*avg(2*x*(a*x+b-y)),
        b-0.05*avg(2*(a*x+b-y))
    from gd, (select * from data tablesample reservoir(1))
    where id<5 group by id,a,b)
    select * from gd order by id;
        Listing 2: Gradient descent (stochastic).</pre>
```

Five iterations, loss function with two weights (8). First, the weights get initialised, then each iteration updates the weights (3) based on manually derived gradients (2) and  $\gamma = 0.05$ .



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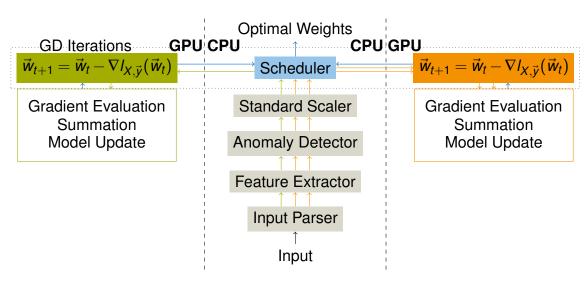
```
create table data (x float, y float);
insert into data ...

with recursive gd (id, a, b) as (
    select 0,1::float,1::float
UNION ALL
    select id+1,
        a-0.05*avg(2*x*(a*x+b-y)),
        b-0.05*avg(2*(a*x+b-y))
    from gd, (select * from data tablesample reservoir(8))
    where id<5 group by id,a,b)
    select * from gd order by id;
        Listing 3: Gradient descent (mini-batch).</pre>
```

Five iterations, loss function with two weights (8). First, the weights get initialised, then each iteration updates the weights (3) based on manually derived gradients (2) and  $\gamma = 0.05$ .



## ML in SQL-92: Components of a Machine Learning Pipeline

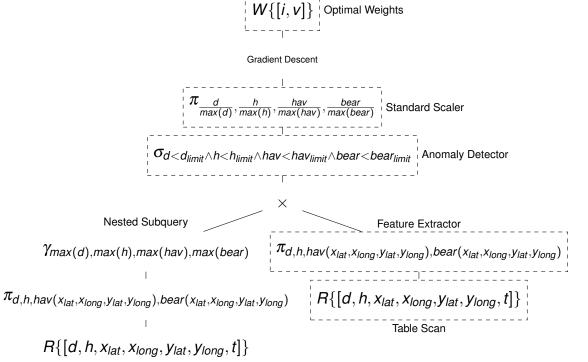


Machine learning pipeline proposed by Derakhshan et. al. (EDBT'19)

- **Scheduler** manages gradient descent iterations until the weights converge.
- Standard Scaler scales all attributes in the range [0,1] to equal each attribute's impact on the model.
- Anomaly Detector deletes tuples on anomalies. An anomaly occurs when at least one attribute in a tuple passes over or under a predefined threshold.
- Feature Extractor: extracts features from data chunks.
- Input Parser: parses input CSV files and stores the data in chunks.



## ML in SQL-92: Machine Learning Pipeline in Relational Algebra



- Standard Scaler: projection and nested subqueries to extract the attribute's extrema (view normalised).
- Anomaly Detector: user-defined limits in a selection (view normalised).
- Feature Extractor: a simple projection in SQL, day and hour from timestamps, distance metrics from given coordinates (view processed).
- Input Parser: a simple table scan or a foreign table as input for continuous views (table taxidata).



# ML in SQL-92: Machine Learning Pipeline in SQL

```
create foreign table taxidata(id int, pickup_datetime date, dropoff_datetime date,
 passengers float, pickup_longitude float, pickup_latitude float, dropoff_longitude float,
 dropoff_latitude float, duration float) server stream;
copy taxidata from './taxidata.csv' delimiter ',';
create view processed as (select hour,day,duration,ACOS(SIN(plat)*SIN(dlat)+COS(plat)*COS(dlat)[...]
create view normalised(hour, day, distance, bearing, duration) as (
 select cast(hour as float)/(select max(hour)+1 from processed), [...]
 from processed where distance < 1000);</pre>
with recursive gd (id, a1, a2, a3, a4, b) as (select 0, 1::float, 1::float, 1::float, 1::float
 UNION ALL select id+1,
   a1-0.001*avg(2*hour*(a1*hour+a2*day+a3*distance+a4*bearing+b-duration)),
   a2-0.001*avg(2*day*(a1*hour+a2*day+a3*distance+a4*bearing+b-duration)),
   a3-0.001*avg(2*distance*(a1*hour+a2*day+a3*distance+a4*bearing+b-duration)),
   a4-0.001*avg(2*bearing*(a1*hour+a2*day+a3*distance+a4*bearing+b-duration)),
   b -0.001*avg(2*(a1*hour+a2*day+a3*distance+a4*bearing+b-duration))
 from gd, (select * from normalised tablesample reservoir (10)) where id<50 group by id,a1,a2,a3,a4, b)
select id, avg(a1*hour+a2*day+a3*distance+a4*bearing+b-duration)^2
 from gd,normalised where id=50;
```

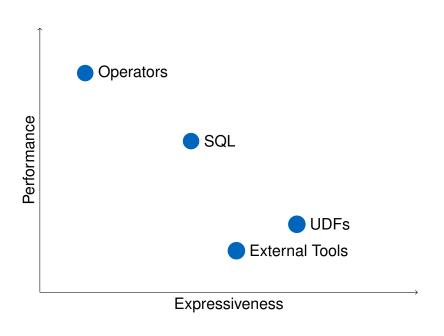


## ML Operators





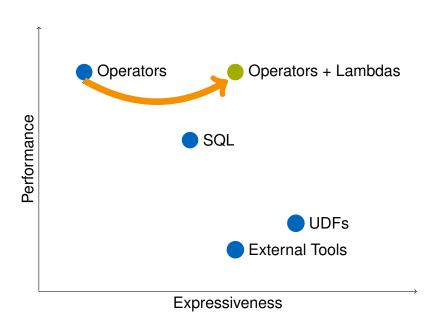
## ML Operators: Why Lambda Functions in SQL?



- SQL
  - Turing-complete with recursive tables
  - queries get optimised before execution
- statements must be expressed in relational algebra
- Operators (Table Functions)
  - purpose-specific but high-performant
  - require development by a database engineer
- User-Defined Functions (UDFs)
  - allow procedural language statements in SQL
  - not as performant as operators
- External Tools
  - database system as storage layer only
  - time consuming extraction necessary



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- External Tools
  - database system as storage layer only
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- Operators + Lambdas
  - customisation of operators



LLVM IR code

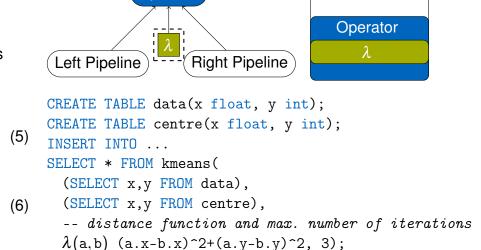
## ML Operators: Lambda Functions in HyPer and Umbra

- HyPer and Umbra: code-generating database systems
- produce LLVM IR (Intermediate Representation)
- Lambda expressions: inject code into regular operators
- composed of lambda arguments to identify tuples and
- a *lambda body* to formulate an expression

$$\lambda(name_1, name_2, ...)(expr)$$

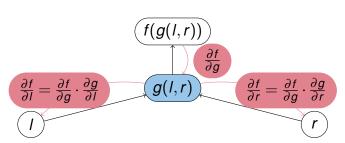
• Example: k-Means with injected distance metric

$$\lambda(S,T)((S.x-T.x)^2+(S.y-T.y)^2)$$

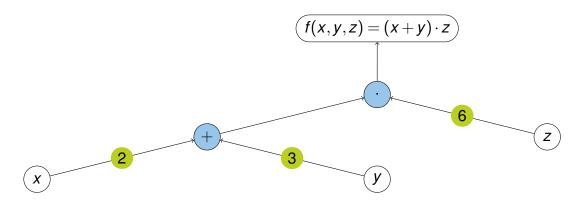


Operator



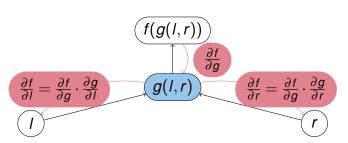


- applying the chain rule to backpropagate the loss
- no need for manually derived gradients
- subexpressions are cached in LLVM registers for reuse
- expose as SQL operator

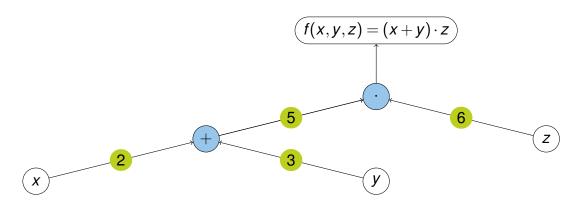


```
select * from umbra.derivation(
   TABLE(select 2 x,3 y,6 z),
   lambda(x)((x.x+x.y)*x.z));
-- x y z d_x d_y d_z
-- 2 3 6 6 6 5
```



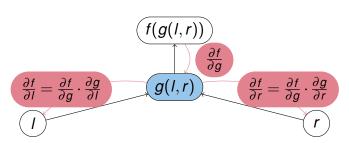


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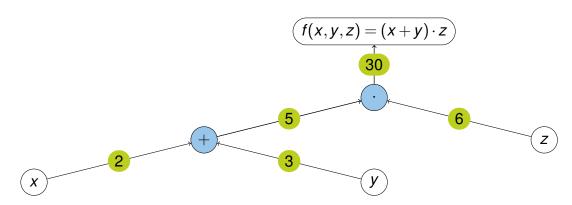


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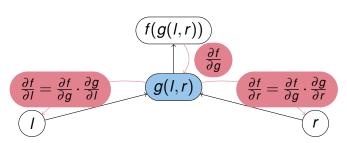


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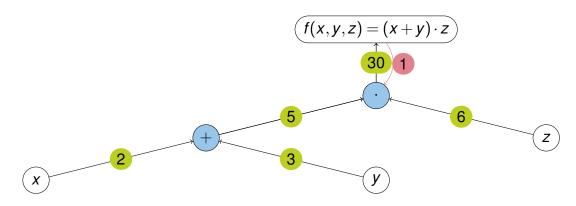


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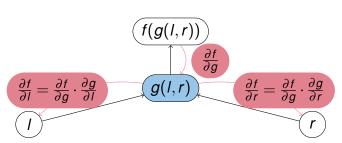


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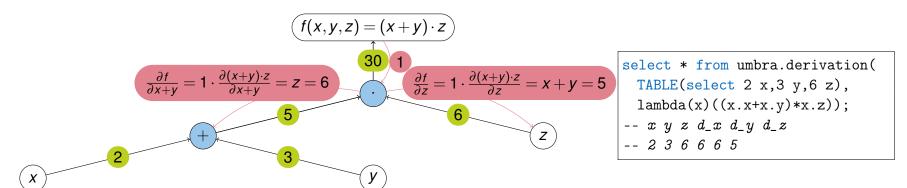


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```

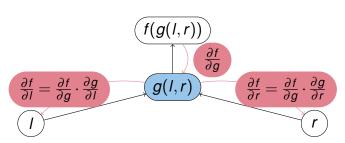




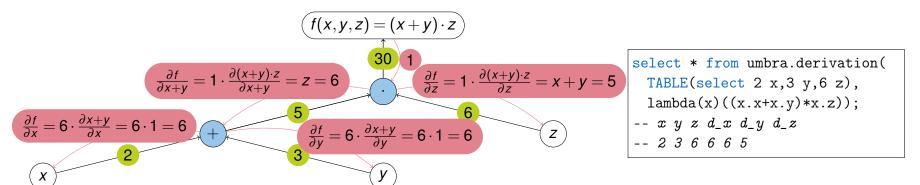
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- expose as SQL operator





## ML Operators: Automatic Differentiation for Gradient Descent

#### **Manually Derived**

# create table data (x float, y float); insert into data ... with recursive gd (id, a, b) as ( select 1,1::float,1::float UNION ALL select id+1, a-0.05\*avg(2\*x\*(a\*x+b-y)), b-0.05\*avg(2\*(a\*x+b-y)) from gd, data where id<5 group by id,a,b) select \* from gd order by id;</pre>

#### **Automatically Derived**

```
create table data (x float, y float);
insert into data ...

with recursive gd (id, a, b) as (
   select 1,1::float,1::float
UNION ALL
   select id+1, a-0.05*avg(d_a), b-0.05*avg(d_b)
   from umbra.derivation(TABLE (
      select id,a,b,x,y from gd,data where id<5),
      lambda (x) ((x.a * x.x + x.b - x.y)^2))
   group by id,a,b)
select * from gd order by id;</pre>
```



## ML Operators: Training a Feed-Forward Neural Network

Fully connected neural network with one hidden layer of size h, L output vector of probabilites, two weight matrices  $w_{xh} \in \mathbb{R}^{|\vec{x}| \times h}$  and  $w_{ho} \in \mathbb{R}^{h \times |L|}$ , an activation function (applied elementwise), model function  $m_{w_{xh},w_{ho}}(\vec{x}) \in \mathbb{R}^{|L|}$ , forward pass and loss:

$$m_{\mathbf{w}_{\mathbf{x}h},\mathbf{w}_{ho}}(\vec{\mathbf{x}}) = sig(sig(\vec{\mathbf{x}}^T \cdot \mathbf{w}_{\mathbf{x}h}) \cdot \mathbf{w}_{ho}), \tag{7}$$

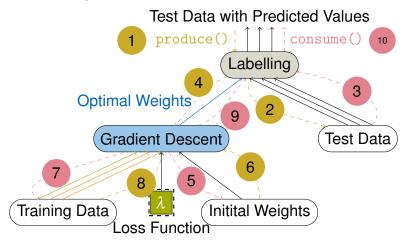
$$I_{W_{xh},W_{ho}}(\vec{x},\vec{y}) = (m_{W_{xh},W_{ho}}(\vec{x}) - \vec{y})^2.$$
 (8)

```
with recursive gd (id,w_xh,w_ho) as (
    select 0, array_fill(0.1::float,array[4,10]), array_fill(0.1::float,array[10,3])
union all
    select id+1, w_xh - 0.1 * avg(d_w_xh), w_ho - 0.1 * avg(d_w_ho)
    from umbra.derivation(TABLE(
        select * from data,gd where id < 10),
        lambda(x)(( sig(sig(x.img*x.w_xh)*x.w_ho) - one_hot)^2 ))
    group by id, w_ho, w_xh)
select * from gd order by id;</pre>
```

Listing 4: Training a neural network when applying matrix algebra on arrays.



## ML Operators: Gradient Descent as Operator



Dedicated operator for gradient descent

- Input: training data, initial weights and the loss function
- Output: optimal weights
- allows to call specialised libraries and off-loading to GPU

```
select * from umbra.gd(
   TABLE (select * from data), TABLE (select 10::float a, 10::float b),
   lambda (x,y) ((y.a * x.x + y.b - x.y)^2), 1, 0.05, 10);
```



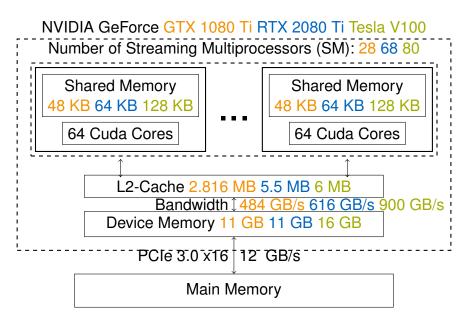


# **GPU Co-Processing**





## GPU Co-Processing: GPU Architecture



- Each GPU device owns one global memory (device memory) and an L2 cache.
- Core components: streaming multiprocessors with an attached shared memory
- Parallel threads perform the same instructions simultaneously
- 32 threads in a bundle: warp, multiple warps: block
- Challenge: map mini-batches of data to blocks
- Parameter: number of warps per block



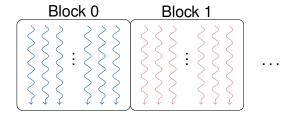
## GPU Co-Processing: Multiple Learner per GPU

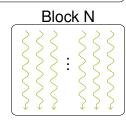
#### **Device Memory**

$$\vec{x}^1, \vec{x}^2, \vec{x}^3, \dots, \vec{x}^{30}, \vec{x}^{31}, \vec{x}^{32}$$
  
 $\vec{x}^{33}, \vec{x}^{34}, \vec{x}^{35}, \dots, \vec{x}^{62}, \vec{x}^{63}, \vec{x}^{64}$ 

#### **Shared Memory**

$$\vec{w}, \vec{w}_{local,0}, \vec{c}_0, \vec{w}_{local,1}, \vec{c}_1, \dots, \vec{w}_{local,N}, \vec{c}_N$$

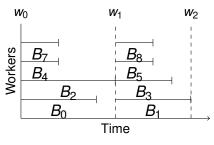


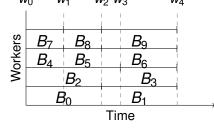


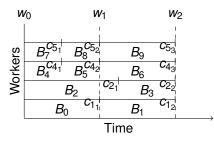
- Goal: utilise all GPU threads even with small batch sizes
- **Solution**: multiple independent learners per GPU
- Each block = one learner, responsible for a mini-batch
- Each learner maintains local weights  $\vec{w}_{local}$  and the difference  $\vec{c}_{local}$  to the global weights  $\vec{w}$ .
- Minimum batch size: one warp (minimum block size) with 32 threads
- Maximum number of learners = number of possible warps



# GPU Co-Processing: Synchronisation







Synchronised threads

Worker threads (global updates)

Worker threads (local models)

- Synchronised threads: same weights with an individual mini-batch, the main worker collects the calculated gradients and takes their average to update the weights, workers might drive idle and waiting for input
- Worker threads (global updates): independent workers have to fetch their mini-batches on their own, global atomic counter as a batch identifier. Weights are updated globally. Assuming a low learning rate, weights are changing marginally and locks can be omitted similar to HogWild.
- Worker threads (local models): local models known from Crossbow: Each learner maintains local weights. For every learner t a vector called corrections  $\vec{c}_t$  stores the differences to the global weights. After each iteration, the corrections of all learners are summed up to form the global weights.





# Evaluation





## Evaluation: Set-Up

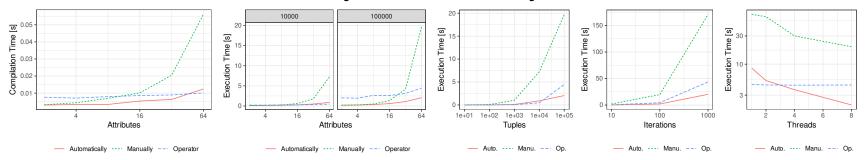
- System: Intel Xeon Gold 5120 processors, 4x14 CPUs (2.20 GHz), Ubuntu 20.04.01 LTS, 256 GiB RAM.
- GPU: either four GPUs (NVIDIA GeForce GTX 1080 Ti/RTX 2080 Ti) or one NVIDIA Tesla V100.
- Models: linear regression and feed-forward neural network with a single hidden layer for image recognition.
- Data: synthetic data, New York taxi data set (January 2015, 2.65 GiB), (Fashion-)MNIST data set

	#attr.	#training	#validation
New York Taxi	4 + 1	61,664,460	15,416,115
Synthetic	99 + 1	10	10
MNIST	784 + 1	60,000	10,000
Fashion-MNIST	784 + 1	60,000	10,000

Table: Training and validation data sets used with linear regression and a neural network respectively.



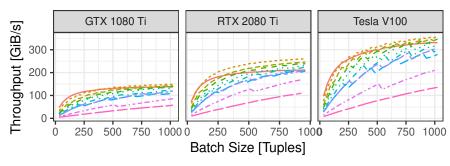
## Evaluation: Automatically vs. Manually Derived

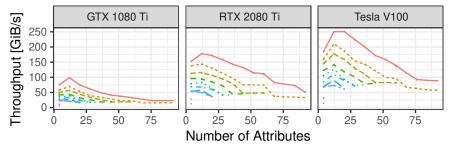


- batch gradient descent (the batch size corresponds to the number of tuples), linear model, synthetic data
- recursive tables with either manually or automatically derived gradients, and a dedicated (single-threaded) operator
- automatic differentiation: speeds up compilation time and execution time (subexpressions are cached in registers for reuse)
- also visible when the batch size, the number of iterations or the number of threads is varied
- parallelisation when using recursive tables



# Evaluation: GPU co-processing (Learners, Linear Regression)





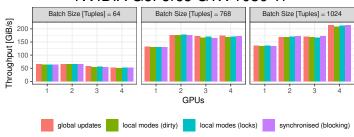
Threads per Learner — 32 --- 96 ··· 160 -- 224 ··- 512
--- 64 -- 128 ·-- 192 --- 256 — 1024

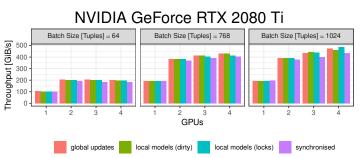
- vary the number of threads per block (32 to 1,024 threads, 4 attributes) or number of attributes (32 threads per block)
- a small number of threads per learner: a higher throughput for small batch sizes.
- highest throughput when batch size is a multiple of the block size
- local maximum (spikes): batch size = multiple of a block size

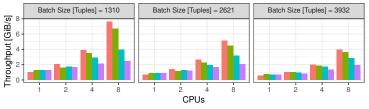


# Evaluation: GPU co-processing (Linear Regression)









local models (dirty) local models (locks)

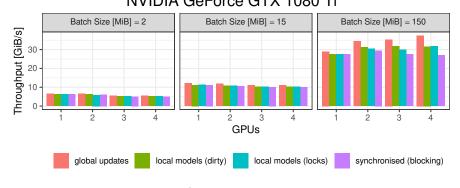
synchronised (blocking)

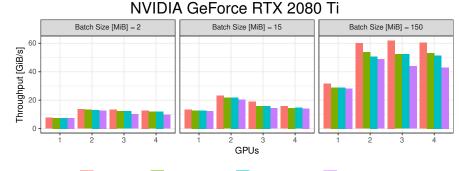
- no synchronisation, global updates (*global updates*), local models with locking of the critical section (*local models (locks)*) or without locking (*local models (dirty)*), (*synchronised (blocking)*).
- CPU: linear speed-up when no synchronisation takes place
- locks: lower throughput, blocking threads cause underutilisation
- GPU: the larger the batch size (less synchronisation), the higher the scale-up as (parallel workers work independently)
- local models: inter-GPU communication decreases the performance with the third additional device



# Evaluation: GPU co-processing (Neural Network)







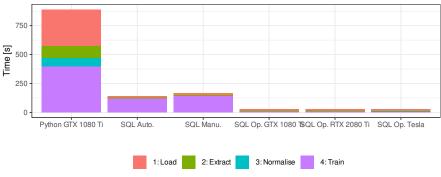
global updates local models (dirty)

- one additional worker increases the throughput
- for any further workers, the inter-GPU communication decreases the runtime
- small batch sizes: best result on two GPU devices
- larger batch sizes: every additional device allows a higher throughput

local models (locks)



## Evaluation: End-to-End



- training of one epoch (New York taxi data: 13 · 10<sup>6</sup> tuples)
- ML pipeline in Python using Keras vs. SQL within Umbra
- Steps: data loading from CSV, feature extraction and normalisation either with NumPy or SQL-92 queries, and training
- much time spent on data loading from CSV and preprocessing (no longer required within a database system or highly parallelised)
- gradient descent using recursive tables: comparable performance to library functions
- all outperformed by our operator that off-loads training to GPU



### Conclusion

- in-database machine learning pipeline expressed in pure SQL based on sampling, continuous views and recursive tables
- operator for automatic differentiation and one for gradient descent
- off-load training to GPU units
- training algorithms as GPU kernels and fine-tuned learners at hardware level to increase the learning throughput
- automatic differentiation accelerated both the compile time and the execution time by the number of cached expressions
- fine-tuned learners at hardware level: highest possible throughput for small batch sizes
- end-to-end machine learning pipeline in SQL: comparable performance to traditional machine learning frameworks



# Thank you for your attention!

